

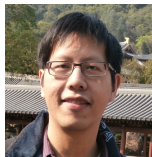
# Delaunay Triangulations with Predictions



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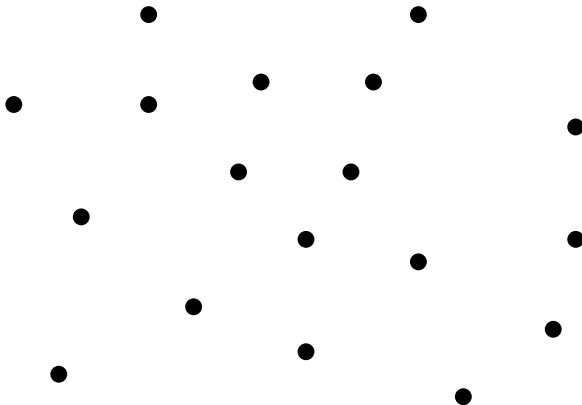


17th Innovations in Theoretical Computer Science (ITCS), 2026

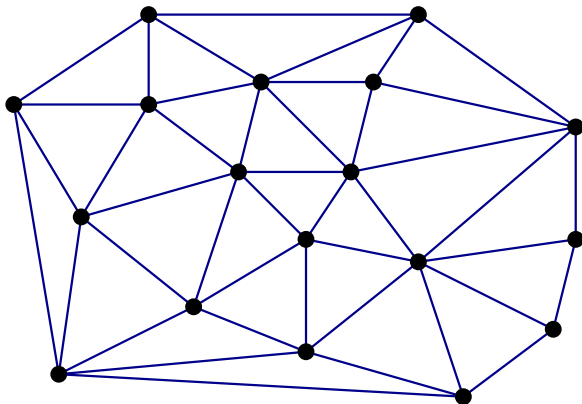


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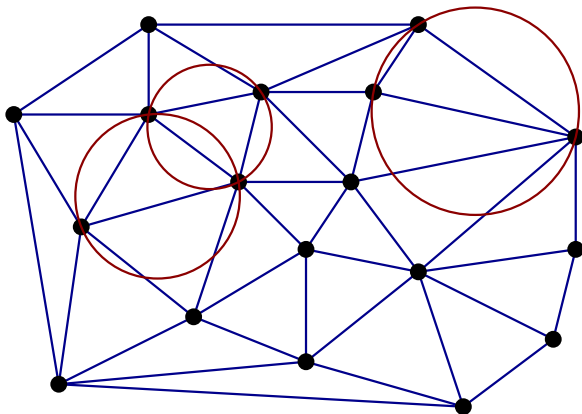
# Delaunay triangulations



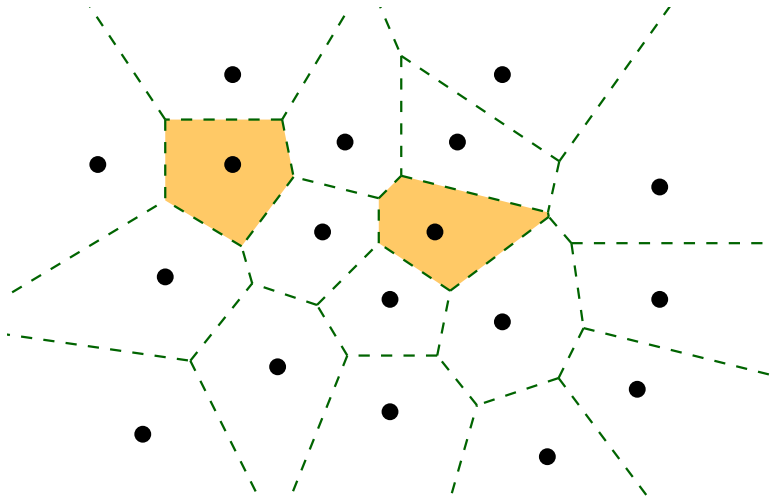
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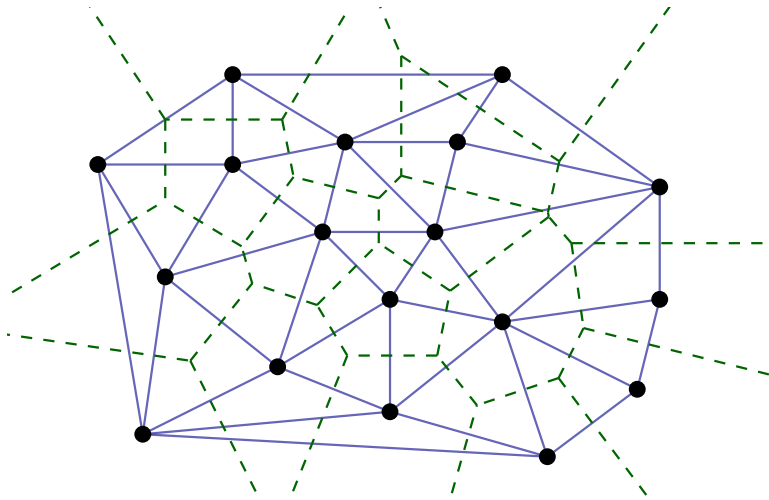
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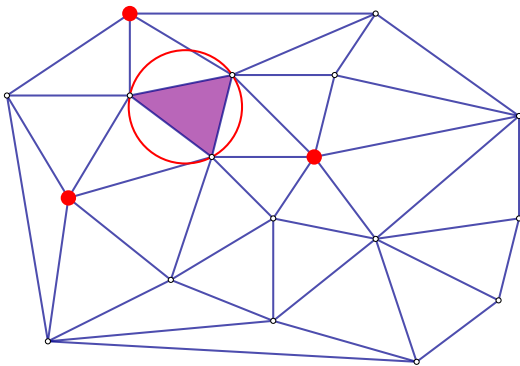


# Delaunay triangulations

- ▶ triangles with empty circumcircle
- ▶ dual to Voronoi diagram
- ▶ lexicographically maximizes the vector of non-decreasing angles
- ▶ partition of the convex hull
- ▶ basic and ubiquitous geometric structure
- ▶ computable in  $O(n \log n)$ , and lower bound of  $\Omega(n \log n)$
- ▶ several paradigms: incremental, randomized incremental, divide and conquer, via Voronoi diagram, via CH in 3d, etc.
- ▶ a 2-dimensional "extension" of sorting

## Delaunay triangulations - locality

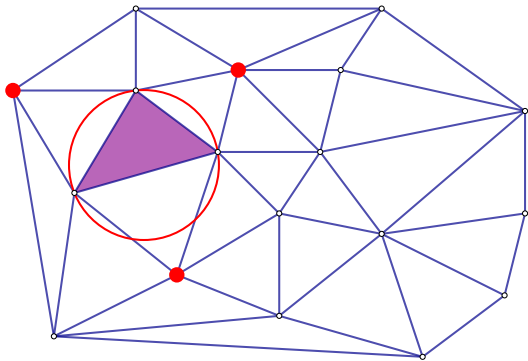
- ▶ testing whether a given triangulation is a Delaunay triangulation
- ▶ suffices local test of each triangle with its  $\leq 3$  neighbor triangles





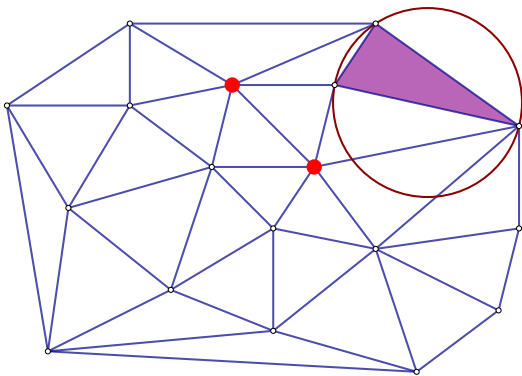
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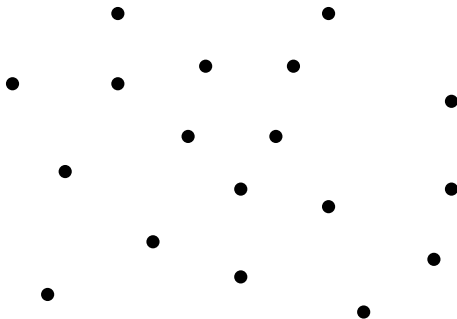


## Delaunay triangulations - locality

- ▶ testing whether a given triangulation is a Delaunay triangulation
- ▶ suffices local test of each triangle with its  $\leq 3$  neighbor triangles
- ▶  $\Theta(n \log n)$  to build Delaunay triangulation
- ▶  $\Theta(n)$  to test if a given triangulation is Delaunay

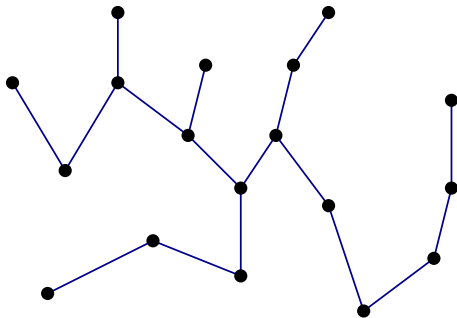
# Euclidean MST

- ▶ Given a set  $P$  of points in  $\mathbb{R}^2$ , compute its Euclidean MST



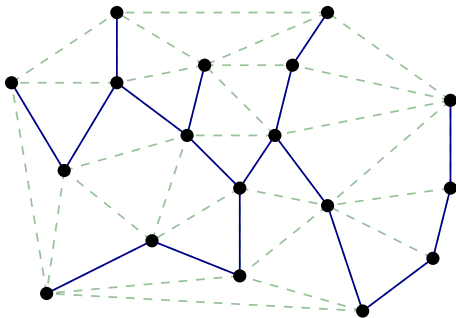
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- ▶  $\text{EMST}(P) \subset \text{DT}(P)$
- ▶  $\text{EMST}(P)$  in  $O(n \log n)$  time via  $\text{DT}(P)$
- ▶ Non-obvious local testing for a candidate  $\text{EMST}(P)$   
 $O(n \log^* n)$  expected time via  $\text{DT}(P)$  [Devillers 1992]

# Predictions

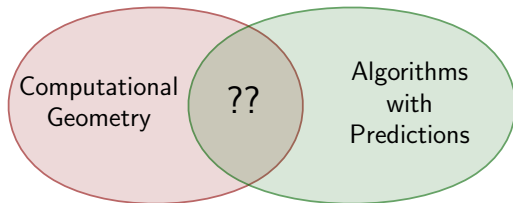
- ▶ **Prediction:** additional information, possibly inaccurate or noisy, which may assist an algorithm to be more effective (= 'better' solution, faster, etc.)
- ▶ Analyze the performance of the algorithm parameterized by how good is the prediction
- ▶ Easy example: sorting a list of numbers that is nearly sorted
- ▶ Prediction: the list itself
- ▶ Parameter: a measure on how sorted the input list is

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- ▶ Analyze the performance of the algorithm parameterized by how good is the prediction
- ▶ Easy example: sorting a list of numbers that is nearly sorted
- ▶ Prediction: the list itself
- ▶ Parameter: a measure on how sorted the input list is
- ▶ Algorithms with predictions [Mitzenmacher, Vassilvitskii '20]
- ▶ Multiple focused events since 2020
- ▶ <https://algorithms-with-predictions.github.io/>  
List of 364 papers as of January 2026



# Our aim

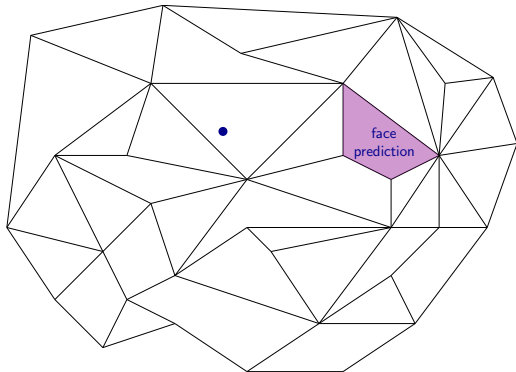


- focus in fundamental object: Delaunay triangulation (and EMST)

## Related work

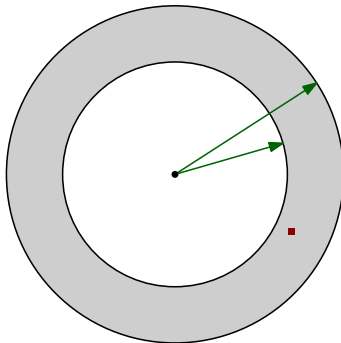
- Point location with a finger

[Iacono, Langerman '03]



## Related work

- ▶ Point location with a finger [Iacono, Langerman '03]
- ▶ Searching a point target in  $\mathbb{R}^d$  with an estimate of the distance to the target [Cabello, Giannopoulos '24]

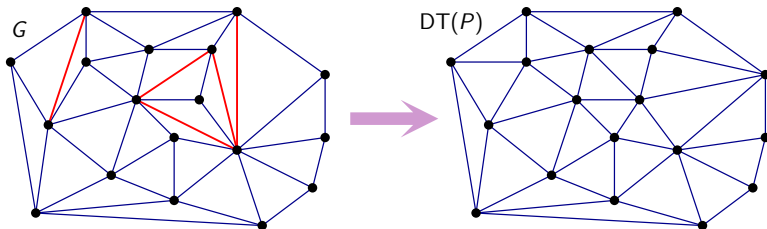


## Related work

- ▶ Point location with a finger [Iacono, Langerman '03]
- ▶ Searching a point target in  $\mathbb{R}^d$  with an estimate of the distance to the target [Cabello, Giannopoulos '24]
- ▶ Computing  $DT(P)$  with additional information:
  - $DT(P)$  from  $EMST(P)$  [Devillers '92]
  - merging:  $DT(P \cup Q)$  from  $DT(P)$  and  $DT(Q)$  [Chazelle '92, Chan '16]
  - splitting:  $DT(P)$  from  $DT(P \cup Q)$  [Chazelle et al '02; Chazelle, Mulzer '11]
- ▶ (Extension of) verification of structures
  - Given a spanning tree of  $P$ , is it  $EMST(P)$ ?

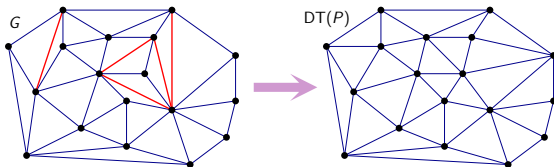
## Sample of our results

- ▶ Input: a set  $P$  of  $n$  points and a **triangulation**  $G$  of  $P$ , hopefully close to  $\text{DT}(P)$
- ▶ Measure of the prediction: (**unknown**) number  $D$  of edges in  $E(G) \setminus \text{DT}(P)$



## Sample of our results

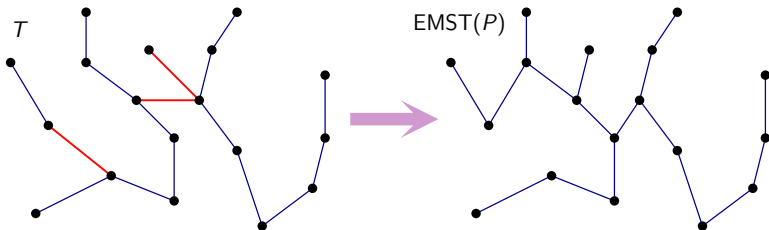
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- ▶ We can compute  $\text{DT}(P)$  in  $O(n + D \log n)$  expected time
- ▶ Smooth interpolation between  $O(n)$  for  $D = 0$  and  $O(n \log n)$  for  $D = \Theta(n)$ .
- ▶ Optimal, randomized
- ▶ Deterministic in  $O(n + D \log^3 n)$

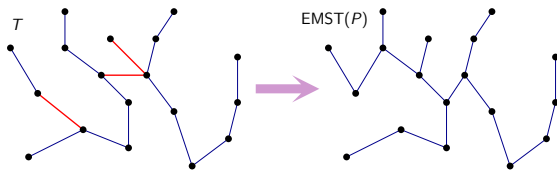
## Sample of our results II

- ▶ Input: a set  $P$  of  $n$  points and a **spanning tree**  $T$  of  $P$ , hopefully similar to  $\text{EMST}(P)$
- ▶ Measure of the prediction:  
(**unknown**) number  $D_{\text{emst}}$  of edges in  $E(T) \setminus E(\text{EMST}(P))$



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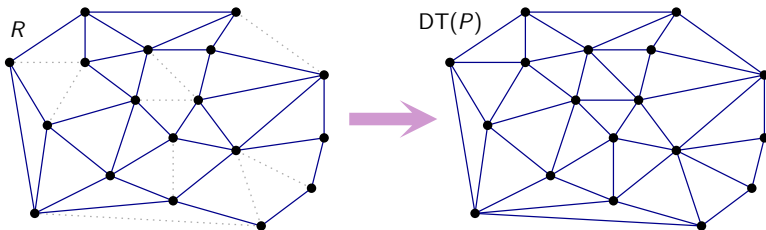
- ▶ We can compute  $\text{EMST}(P)$  in  $O((n + D_{\text{emst}} \log n) \log^* n)$  expected time
- ▶ When  $D = 0$ , we recover the  $O(n \log^* n)$  for testing



## Sample of our results III

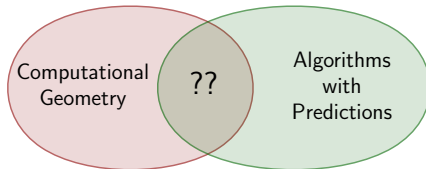
Model with probabilistic noise

- ▶  $R \subset_{\text{random}} E(\text{DT}(P))$   
each edge selected independently with probability  $\rho$
- ▶  $G$  a triangulation **extending**  $R$ , or  $R$  with info about embedding
- ▶ Measure of the prediction: (**unknown**) probability  $\rho$



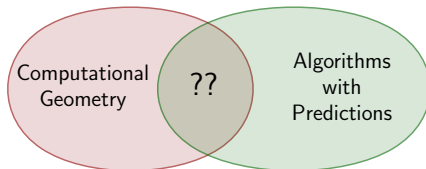
- ▶ We can compute  $\text{DT}(P)$  in  $O(n \log \log n + n \log(1/\rho))$  whp
- ▶ For  $\rho = 1/\log n$  a small fraction of  $E(\text{DT}(P))$  is kept

# Conclusions



- ▶ New paradigm in Computational Geometry
- ▶ Basic premise: checking correctness faster than constructing from scratch
- ▶ We also use other measures of how close to  $DT(P)$
- ▶ Some of our optimal algorithms are randomized.  
Deterministic?
- ▶ Some other algorithms are (not expected?) to be optimal  $\log^* n$  and  $\log \log n$  factors?

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THANKS for your time!!