

# Every meromorphic function is the Gauss map of a conformal minimal surface

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Conversely, if a nowhere vanishing holomorphic 1-form  $\Phi = (\phi_1, \dots, \phi_n)$  on  $M$  satisfies (1) and has vanishing real periods:

$$\int_{\gamma} \Re(\Phi) = 0 \quad \text{for all } \gamma \in H_1(M; \mathbb{Z}),$$

then the integral of  $\Re\Phi$  is a conformal minimal immersion  $M \rightarrow \mathbb{R}^n$ :

$$X(p) = \int_*^p 2\Re\Phi, \quad p \in M.$$

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where

$$f: M \rightarrow \mathcal{A}_*^{n-1} = \mathcal{A}^{n-1} \setminus \{0\} \subset \mathbb{C}^n$$

is a holomorphic map with values in the **null quadric**

$$\mathcal{A}^{n-1} = \{(z_1, \dots, z_n) \in \mathbb{C}^n : z_1^2 + z_2^2 + \dots + z_n^2 = 0\}$$

such that

the 1-form  $f\theta$  has vanishing real periods.

# Flux and holomorphic null curves

The **flux** of a conformal minimal immersion  $X: M \rightarrow \mathbb{R}^n$  is the group homomorphism

$$\text{Flux}_X: H_1(M; \mathbb{Z}) \rightarrow \mathbb{R}^n$$

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$$\text{Flux}_X(\gamma) = \int_{\gamma} \Im(\partial X) = \int_{\gamma} d^c X \quad \text{for every closed curve } \gamma \subset M.$$

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$$X = \Re(Z)$$

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This always holds if  $M$  is simply connected (the disk or the plane).

# The generalized Gauss map

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Since the 1-form  $\partial X = (\partial X_1, \dots, \partial X_n)$  is holomorphic and nowhere vanishing, it determines the Kodaira type holomorphic map

$$G_X: M \rightarrow \mathbb{C}P^{n-1}, \quad G_X(p) = [\partial X_1(p) : \dots : \partial X_n(p)] \quad (p \in M).$$

The map  $G_X$  is known as the **generalized Gauss map of  $X$**  and is of great importance in the theory of minimal surfaces.

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Since  $\sum_{j=1}^n (\partial X_j)^2 = 0$ ,  $G_X$  assumes values in the complex hyperquadric

$$Q^{n-2} = \{[z_1 : \dots : z_n] \in \mathbb{C}\mathbb{P}^{n-1} : z_1^2 + \dots + z_n^2 = 0\} = \pi(\mathcal{A}_*^{n-1})$$

where  $\pi: \mathbb{C}^n \rightarrow \mathbb{C}\mathbb{P}^{n-1}$  denotes the canonical projection.

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If in addition the map  $\mathcal{G}$  is **full** (i.e., its image is not contained in any proper projective subspace), then  $X$  can be chosen to have arbitrary flux and to be an embedding if  $n \geq 5$  and an immersion with simple double points if  $n = 4$ .

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If  $M$  and  $\mathcal{G}$  are algebraic (so  $M = \overline{M} \setminus \{p_1, \dots, p_m\}$  with  $\overline{M}$  a closed Riemann surface), we don't know whether  $X$  can be chosen algebraic.

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To prove the theorem, we construct a holomorphic multiplier  $h: M \rightarrow \mathbb{C}_*$  such that the  $\mathbb{C}^n$ -valued holomorphic 1-form

$$\Phi = hf\theta = h(f_1, \dots, f_n)\theta$$

has vanishing periods, so it integrates to a conformal minimal immersion

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Then,  $\partial X = \Phi$  and hence  $G_X = \mathcal{G}$ .

## The case $n = 3$

The quadric  $Q^1 \subset \mathbb{C}\mathbb{P}^2$  is an embedded rational curve  $\mathbb{C}\mathbb{P}^1 \hookrightarrow \mathbb{C}\mathbb{P}^2$ , and the *complex Gauss map* of a conformal minimal immersion  $X = (X_1, X_2, X_3): M \rightarrow \mathbb{R}^3$  is defined to be the holomorphic map

$$g_X = \frac{\partial X_3}{\partial X_1 - i\partial X_2} = \frac{\partial X_2 - i\partial X_1}{i\partial X_3} : M \longrightarrow \mathbb{C}\mathbb{P}^1.$$

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The function  $g_X$  is the stereographic projection of the real Gauss map  $N = (N_1, N_2, N_3): M \rightarrow \mathbb{S}^2 \subset \mathbb{R}^3$  to the Riemann sphere  $\mathbb{C}\mathbb{P}^1$ :

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### Corollary

*Let  $M$  be an open Riemann surface. Every holomorphic map  $g: M \rightarrow \mathbb{C}\mathbb{P}^1$  is the complex Gauss map of a conformal minimal immersion  $X: M \rightarrow \mathbb{R}^3$  with vanishing flux.*

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*If  $g$  is nonconstant, then we can find  $X$  with arbitrary given flux.*

# Metric and curvature

We can recover  $\partial X = (\partial X_1, \partial X_2, \partial X_3)$  from the pair  $(g_X, \phi_3)$  with  $\phi_3 = \partial X_3$  by the classical [Weierstrass formula](#)

$$\partial X = \Phi = (\phi_1, \phi_2, \phi_3) = \left( \frac{1}{2} \left( \frac{1}{g_X} - g_X \right), \frac{i}{2} \left( \frac{1}{g_X} + g_X \right), 1 \right) \phi_3.$$

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$$ds_X^2 = X^*(ds_{\mathbb{R}^3}^2) = \frac{1}{2} \sum_{j=1}^3 |\phi_j|^2 = \frac{(1 + |g|^2)^2}{4|g|^2} |\phi_3|^2 \quad (\text{the induced metric}),$$

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$$K = - \left( \frac{4|g| \cdot |dg|}{|\phi_3|(1 + |g|^2)^2} \right)^2 \quad (\text{the Gauss curvature}).$$

# A brief history of the Gauss map of minimal surfaces

In dimension 3, the complex Gauss map is really fundamental in the theory; it completely determines several important geometric properties of the minimal surface, and there is a huge literature devoted to it.

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**Voss 1964** Let  $k \leq 4$ . For any  $k$  points  $a_1, \dots, a_k \in \mathbb{CP}^1$  there exists a complete nonflat minimal surface  $X: \mathbb{CP}^1 \setminus \{a_1, \dots, a_k\} \rightarrow \mathbb{R}^3$  whose Gauss map omits precisely the set  $a_1, \dots, a_k$ .

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**Voss 1964** Let  $k \leq 4$ . For any  $k$  points  $a_1, \dots, a_k \in \mathbb{C}P^1$  there exists a complete nonflat minimal surface  $X: \mathbb{C}P^1 \setminus \{a_1, \dots, a_k\} \rightarrow \mathbb{R}^3$  whose Gauss map omits precisely the set  $a_1, \dots, a_k$ .

**Fujimoto 1988** The Gauss map of a complete nonflat minimal surface cannot omit 5 points of the sphere. (**Xavier 1981:** It cannot omit 7 points. **López and Ros 1987:** it cannot omit 6 points.)

# Stable minimal surfaces in $\mathbb{R}^3$

A minimal surface  $S \subset \mathbb{R}^3$  is said to be **stable** if any relatively compact smoothly bounded domain  $D \Subset S$  has minimal area among all small variations of  $\overline{D}$  which keep the boundary  $\partial D$  fixed.

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Let  $X: M \rightarrow \mathbb{R}^3$  be a conformal minimal immersion. The minimal surface  $X(M) \subset \mathbb{R}^3$  is stable if the spherical image  $g_X(M) \subset \mathbb{C}\mathbb{P}^1$  of its Gauss map  $g_X$  has area less than  $2\pi = \frac{1}{2}\text{Area}(\mathbb{C}\mathbb{P}^1)$ .

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## Corollary

*If  $M$  is an open Riemann surface and  $g: M \rightarrow \mathbb{C}P^1$  is a holomorphic map whose image  $g(M)$  has area less than  $2\pi$ , then there exists a stable conformal minimal immersion  $M \rightarrow \mathbb{R}^3$  with the complex Gauss map  $g$ .*

# Isotopies whose Gauss map omits two points

## Theorem

*Given an open Riemann surface  $M$  and a conformal minimal immersion  $X: M \rightarrow \mathbb{R}^3$ , there exists an isotopy*

$$X_t: M \rightarrow \mathbb{R}^3, \quad t \in [0, 1]$$

*of conformal minimal immersions such that  $X_0 = X$  and the complex Gauss map  $g = g_{X_1}: M \rightarrow \mathbb{C}\mathbb{P}^1$  of  $X_1$  is nonconstant and avoids any two given points of the Riemann sphere.*

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*There also exists an isotopy  $X_t$  as above such that  $X_0 = X$  and  $X_1$  is flat, so its Gauss map  $g$  is constant.*

# The main complex analytic result

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be a continuous family of group homomorphisms. Then, there exists a continuous family of holomorphic multipliers

$$h_t: M \rightarrow \mathbb{C}_*, \quad t \in [0, 1]$$

such that

$$\int_{\gamma} h_t \Phi_t = q_t(\gamma) \quad \text{for every closed curve } \gamma \subset M \text{ and } t \in [0, 1].$$

# Proof

A desired family of holomorphic multipliers  $h_t: M \rightarrow \mathbb{C}_*$  ( $t \in I = [0, 1]$ ) is constructed by a recursive procedure with respect to an exhaustion of  $M$  by an increasing sequence of smoothly bounded Runge domains

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- **Mergelyan's approximation theorem** is used to approximate continuous families of multipliers on Runge domains with attached curves by continuous families of holomorphic multipliers.

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Set  $I = [0, 1]$ . Given continuous maps

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such that  $f_t := f(t, \cdot): I \rightarrow \mathbb{C}^n$  is *nowhere flat* for every  $t \in I$ , there exists a continuous function  $h: I^2 \rightarrow \mathbb{C}_*$  such that

$$\int_0^1 h(t, s) f(t, s) ds = \alpha(t), \quad t \in I$$

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In addition,

$$\int_0^1 f(0, s) ds = \alpha(0) \implies h(0, \cdot) \equiv 1.$$

# Proof of Lemma 1, part 1

It suffices to prove that for any  $\epsilon > 0$  there exists  $h: I^2 \rightarrow \mathbb{C}_*$  such that

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The exact result is obtained by splitting  $I = I_1 \cup I_2 = [0, 1/2] \cup [1/2, 1]$ , applying the approximate result with a small  $\epsilon > 0$  on  $I_1$  and a period dominating argument on  $I_2$  (see Lemma 2 below) to correct the error.

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Set

$$V_j(t) = \int_{s_{j-1}}^{s_j} f_t(s) ds \approx f_t(s_j)(s_j - s_{j-1}), \quad j = 1, \dots, N.$$

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By passing to a finer division of  $I$ , we may therefore assume that

$$\text{span}\{V_1(t), \dots, V_N(t)\} = \mathbb{C}^n, \quad t \in I.$$

## Proof of Lemma 1, part 2

For each  $t \in I$  we let  $\Sigma_t \subset \mathbb{C}^N$  denote the affine complex hyperplane

$$\Sigma_t = \{(g_1, \dots, g_N) \in \mathbb{C}^N : \sum_{j=1}^N g_j V_j(t) = \alpha(t)\}.$$

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Hence, if  $\int_0^1 f(0, s) ds = \alpha(0)$  then  $g$  can be chosen such that  $g(0) = (1, \dots, 1) \in \mathbb{C}^N$ . We assume in the sequel that this holds.

## Proof of Lemma 1, part 3

By a small perturbation we may assume that  $g_j(t) \in \mathbb{C}_*$  for every  $t \in I$  and  $j = 1, \dots, N$ . (We use general position and  $\dim I = 1$ .) This changes the exact condition in the above display to the approximate condition

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$$\left| \int_0^1 h(t, s) f(t, s) ds - \alpha(t) \right| < \epsilon, \quad t \in I.$$

This completes the proof of Lemma 1.

# Period dominating families of multipliers

## Lemma (2)

*Let  $I'$  be a nontrivial closed subinterval of  $I = [0, 1]$ , let  $Q$  be a compact Hausdorff space (we may use  $Q = I$ ), and let  $n \in \mathbb{N}$ .*

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Given a continuous map  $f: Q \times I \rightarrow \mathbb{C}^n$  such that  $f(q, \cdot)$  is full on  $I'$  for every  $q \in Q$ , there exist finitely many continuous functions  $g_1, \dots, g_N: I \rightarrow \mathbb{C}$  ( $N \geq n$ ), supported on  $I'$ , such that the function  $h: \mathbb{C}^N \times I \rightarrow \mathbb{C}$  given by

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is a **period dominating multiplier of  $f$** , meaning that the map

$$\frac{\partial}{\partial \zeta} \Big|_{\zeta=0} \int_0^1 h(\zeta, s) f(q, s) ds: T_0 \mathbb{C}^N \cong \mathbb{C}^N \rightarrow \mathbb{C}^n$$

is surjective for every  $q \in Q$ .

## Proof of Lemma 2, part 1

Let  $N \geq n$  be an integer and, for each  $i \in \{1, \dots, N\}$ , let  $g_i: I \rightarrow \mathbb{C}$  be a continuous function supported on  $I'$  (to be specified later).

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Let  $\mathcal{P}: Q \times \mathbb{C}^N \rightarrow \mathbb{C}^n$  be the map given by

$$\mathcal{P}(q, \zeta) = \int_0^1 h(\zeta, s) f(q, s) ds, \quad (q, \zeta) \in Q \times \mathbb{C}^N.$$

# Proof of Lemma 2, part 1

Let  $N \geq n$  be an integer and, for each  $i \in \{1, \dots, N\}$ , let  $g_i: I \rightarrow \mathbb{C}$  be a continuous function supported on  $I'$  (to be specified later).

Let  $\zeta = (\zeta_1, \dots, \zeta_N)$  be coordinates on  $\mathbb{C}^N$ . Set

$$h(\zeta, s) := 1 + \sum_{i=1}^N \zeta_i g_i(s), \quad (\zeta, s) \in \mathbb{C}^N \times I$$

and note that

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Then

$$\left. \frac{\partial \mathcal{P}(q, \zeta)}{\partial \zeta_i} \right|_{\zeta=0} = \int_0^1 \left. \frac{\partial h(\zeta, s)}{\partial \zeta_i} \right|_{\zeta=0} f(q, s) ds = \int_0^1 g_i(s) f(q, s) ds.$$

## Proof of Lemma 2, part 2

Since  $f(q, \cdot)$  is full on  $I'$  for every  $q \in Q$ , there are distinct points  $s_1, \dots, s_N$  in the interior of  $I'$  for a big  $N \in \mathbb{N}$  such that

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Let  $\epsilon > 0$  be small enough such that the intervals  $[s_i - \epsilon, s_i + \epsilon]$  ( $i = 1, \dots, N$ ) are pairwise disjoint and contained in  $I'$ . Let  $g_i: I \rightarrow \mathbb{C}$  be continuous function supported on  $(s_i - \epsilon, s_i + \epsilon) \subset I'$  and satisfying

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It follows that

$$\left. \frac{\partial \mathcal{P}(q, \zeta)}{\partial \zeta_i} \right|_{\zeta=0} = \int_0^1 g_i(s) f(q, s) ds \approx f(q, s_i)$$

for all  $q \in Q$  and  $i \in \{1, \dots, N\}$ .

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for all  $q \in Q$  and  $i \in \{1, \dots, N\}$ . Therefore, if  $\epsilon > 0$  is small enough,

$$\text{span} \left\{ \left. \frac{\partial \mathcal{P}(q, \zeta)}{\partial \zeta_1} \right|_{\zeta=0}, \dots, \left. \frac{\partial \mathcal{P}(q, \zeta)}{\partial \zeta_N} \right|_{\zeta=0} \right\} = \mathbb{C}^n \quad \text{for all } q \in Q.$$

This completes the proof of Lemma 2.

# Construction of the multiplier on $M$

We exhaust  $M$  by smoothly bounded Runge domains  $D_1 \subset D_2 \subset \cdots \cup_j D_j = M$  such that  $D_{j+1}$  is obtained from  $D_j$  by adding at most one handle, or a new connected component.

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**The noncritical case:** there is no change of topology for  $D_j \subset D_{j+1}$ . We embed the multiplier  $h: D_j \rightarrow \mathbb{C}_*$  in a period dominating family  $h_\zeta: D_j \rightarrow \mathbb{C}_*$  ( $\zeta \in \mathbb{C}^N$ ) with  $h = h_0$ .

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**Step 2:** Use Lemma 2 to embed the multiplier into a period dominating family over  $D_j \cup E$ . Now proceed as in the noncritical case.

# The h-principle for conformal minimal immersions

$\mathfrak{N}_*(M, \mathbb{C}^n)$ : nonflat holomorphic null curves  $M \rightarrow \mathbb{C}^n$

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$$\begin{array}{ccccc} \mathfrak{N}_*(M, \mathbb{C}^n) & \xrightarrow{\phi} & \mathcal{O}(M, \mathcal{A}_*^{n-1}) & \hookrightarrow & \mathcal{C}(M, \mathcal{A}_*^{n-1}) \\ \mathfrak{R} \downarrow & & \uparrow \psi & & \\ \mathfrak{RN}_*(M, \mathbb{C}^n) & \xrightarrow{\iota} & \mathfrak{M}_*(M, \mathbb{R}^n) & & \end{array}$$

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Since  $\mathcal{A}_*$  is an **Oka manifold**, the inclusion  $\mathcal{O}(M, \mathcal{A}_*) \hookrightarrow \mathcal{C}(M, \mathcal{A}_*)$  is a weak homotopy equivalence by the **Oka-Grauert principle**.

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**Theorem (F. Lárusson and F. F., 2016)**

*Each of the maps  $\iota$ ,  $\phi$ ,  $\psi$  is a weak homotopy equivalence, and a strong homotopy equivalence if  $H_1(M; \mathbb{Z})$  is finitely generated.*

# The h-principle for conformal minimal immersions

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The theorem tells us that these mapping spaces all have the same weak homotopy type as the space  $\mathfrak{H} = \mathcal{C}(M, \mathcal{A}_*^{n-1})$ .

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**Thus, the structure of  $\mathfrak{H}$  can be understood in terms of spheres and their loop spaces. The homotopy groups of  $\mathfrak{H}$  can be calculated in terms of homotopy groups of spheres.**

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**Today, we look at the path connected components of  $\mathfrak{H}$  and leave the rest for another day.**

# Path components of the space $\mathfrak{M}_*(M, \mathbb{R}^n)$

## Corollary

Let  $H_1(M; \mathbb{Z}) = \mathbb{Z}^\ell$  with  $\ell \in \mathbb{Z}_+ \cup \{\infty\}$ . Then

$$\pi_0(\mathfrak{M}_*(M, \mathbb{R}^3)) = (\mathbb{Z}_2)^\ell, \quad \pi_0(\mathfrak{M}_*(M, \mathbb{R}^n)) = 0 \text{ if } n > 3.$$

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**Proof.** By the theorem, the path components of  $\mathfrak{M}_*(M, \mathbb{R}^n)$  agree with those of  $\mathcal{C}(M, \mathcal{A}_*^{n-1})$ .

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$$\pi_1(\mathcal{A}_*^2) = H_1(\mathcal{A}_*^2; \mathbb{Z}) = \mathbb{Z}_2, \quad \pi_1(\mathcal{A}_*^{n-1}) = 0 \text{ if } n > 3.$$

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Thus, the path components of  $\mathcal{C}(M, \mathcal{A}_*^2)$  are in bijective correspondence with group homomorphisms

$$H_1(M; \mathbb{Z}) \cong \mathbb{Z}^\ell \rightarrow \mathbb{Z}_2,$$

hence with elements of  $(\mathbb{Z}_2)^\ell$ .

# Path components of the space $\mathfrak{M}_*(M, \mathbb{R}^n)$

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Let  $H_1(M; \mathbb{Z}) = \mathbb{Z}^\ell$  with  $\ell \in \mathbb{Z}_+ \cup \{\infty\}$ . Then

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**Proof.** By the theorem, the path components of  $\mathfrak{M}_*(M, \mathbb{R}^n)$  agree with those of  $\mathcal{C}(M, \mathcal{A}_*^{n-1})$ . We have

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hence with elements of  $(\mathbb{Z}_2)^\ell$ .

If  $n > 3$  then  $\mathcal{C}(M, \mathcal{A}_*^{n-1})$  is path connected since  $\pi_1(\mathcal{A}_*^{n-1}) = 0$ .

# Path components of the space $\mathfrak{M}(M, \mathbb{R}^n)$

$\mathfrak{M}(M, \mathbb{R}^n)$  = the space of all conformal minimal immersions  $M \rightarrow \mathbb{R}^n$ .

**Theorem (A. Alarcón, F.J. López, F.F., 2016)**

*Let  $M$  be an open connected Riemann surface. The natural inclusion*

$$\mathfrak{M}_*(M, \mathbb{R}^n) \hookrightarrow \mathfrak{M}(M, \mathbb{R}^n)$$

*induces a bijection of path components of the two spaces. In particular,*

$$\pi_0(\mathfrak{M}(M, \mathbb{R}^3)) \cong (\mathbb{Z}_2)^\ell \quad \text{where } H_1(M; \mathbb{Z}) = \mathbb{Z}^\ell,$$

*and  $\mathfrak{M}(M, \mathbb{R}^n)$  is path connected if  $n > 3$ .*

# Path components of the space $\mathfrak{M}(M, \mathbb{R}^n)$

$\mathfrak{M}(M, \mathbb{R}^n)$  = the space of all conformal minimal immersions  $M \rightarrow \mathbb{R}^n$ .

## Theorem (A. Alarcón, F.J. López, F.F., 2016)

*Let  $M$  be an open connected Riemann surface. The natural inclusion*

$$\mathfrak{M}_*(M, \mathbb{R}^n) \hookrightarrow \mathfrak{M}(M, \mathbb{R}^n)$$

*induces a bijection of path components of the two spaces. In particular,*

$$\pi_0(\mathfrak{M}(M, \mathbb{R}^3)) \cong (\mathbb{Z}_2)^\ell \quad \text{where } H_1(M; \mathbb{Z}) = \mathbb{Z}^\ell,$$

*and  $\mathfrak{M}(M, \mathbb{R}^n)$  is path connected if  $n > 3$ .*

The case  $n > 3$  is a corollary to the following result.

## Theorem (Deforming flat immersions to nonflat ones)

*Given a flat conformal minimal immersion  $X: M \rightarrow \mathbb{R}^n$  ( $n \geq 3$ ), there exists an isotopy  $X_t: M \rightarrow \mathbb{R}^n$  ( $t \in [0, 1]$ ) of conformal minimal immersions such that  $X_0 = X$  and  $X_1$  is nonflat.*

# Proof of the deformation theorem

We may assume that  $n = 3$  and  $\partial X = (1, i, 0)\phi_3$  where  $\phi_3$  is an exact holomorphic 1-form without zeros on  $M$ .

The gist of the proof is show that there is nonconstant holomorphic function  $g: M \rightarrow \mathbb{C}_*$  such that  $g\phi_3$  and  $g^2\phi_3$  are exact 1-forms on  $M$ . This is similar to the proof of Lemma 1. Then,

$$\Phi_\lambda = \left(1 - \lambda^2 g^2, i(1 + \lambda^2 g^2), 2\lambda g\right) \phi_3, \quad \lambda \in \mathbb{C}$$

is an exact holomorphic 1-form and the map  $\Phi_\lambda/\phi_3$  assumes values in the punctured null quadric  $\mathcal{A}_* \subset \mathbb{C}^3$  for every  $\lambda \in \mathbb{C}$ . Thus,  $\Phi_\lambda$  provides a conformal minimal immersion  $X_\lambda: M \rightarrow \mathbb{R}^3$  by

$$X_\lambda(p) = X(p_0) + 2 \int_{p_0}^p \Re(\Phi_\lambda), \quad p \in M.$$

Since  $\Phi_0 = \partial X$ , we have that  $X_0 = X$ . Furthermore, since  $g$  is nonconstant,  $X_1$  is nonflat, and hence the isotopy  $X_t: M \rightarrow \mathbb{R}^n$  ( $t \in [0, 1]$ ) satisfies the conclusion of the theorem.

# Path components of the space $\mathfrak{M}(M, \mathbb{R}^3)$

In dimension  $n = 3$ , we obtain that

$$\pi_0(\mathfrak{M}(M, \mathbb{R}^3)) = \mathbb{Z}_2^\ell$$

by using the corresponding result for nonflat immersions,

$$\pi_0(\mathfrak{M}_*(M, \mathbb{R}^3)) = \mathbb{Z}_2^\ell,$$

along with the deformation theorem and the following result.

## Theorem

Let  $\theta$  be a nowhere vanishing holomorphic 1-form on  $M$ . For every group homomorphism

$$p: H_1(M; \mathbb{Z}) \cong \mathbb{Z}^\ell \rightarrow \mathbb{Z}_2$$

there exists a **flat conformal minimal immersion**  $X: M \rightarrow \mathbb{R}^3$  satisfying  $H_1(\partial X/\theta) = p$ .

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We have also obtained new results on **holomorphic Legendrian curves**, i.e., integral curves of the **holomorphic contact form** on  $\mathbb{C}^{2n+1}$ :

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