

Holomorphic Flexibility Properties of Compact Complex Surfaces

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We introduce the notion of a stratified Oka manifold and prove that such a manifold X is strongly dominable in the sense that, for every $x \in X$, there is a holomorphic map $f: \mathbb{C}^n \rightarrow X$, $n = \dim X$, such that $f(0) = x$ and f is a local biholomorphism at 0. We deduce that every Kummer surface is strongly dominable. We determine which minimal compact complex surfaces of class VII are Oka, assuming the global spherical shell conjecture. We deduce that the Oka property and several weaker holomorphic flexibility properties are in general not closed in families of compact complex manifolds. Finally, we consider the behavior of the Oka property under blowing up and blowing down.

1 Introduction

The class of Oka manifolds has emerged from the modern theory of the Oka principle, initiated in 1989 in a seminal paper of Gromov [16]. They were first formally defined by the first-named author in 2009 in the wake of his result that some dozen possible definitions are all equivalent [12]. A complex manifold X is said to be an *Oka manifold* if the homotopy principle holds for maps from Stein sources into X , meaning that every continuous map from a Stein manifold (or, more generally, a reduced Stein space)

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S into X can be deformed to a holomorphic map, with interpolation on a closed complex subvariety of S , uniform approximation on a holomorphically convex compact subset of S , and with continuous dependence on a parameter. Equivalently, for every $n \geq 1$, every holomorphic map from an open neighborhood of a convex compact subset K of \mathbb{C}^n to X can be uniformly approximated on K by entire maps $\mathbb{C}^n \rightarrow X$. This property, the *convex approximation property*, is the weakest version of the Oka property. Looking at the Oka property formulated this way, it is immediate that it passes up and down any holomorphic covering map. More generally, and this is not quite as easy to see, the Oka property passes up and down in any holomorphic fiber bundle with Oka fibers.

The Oka property can be seen as an answer to the question: what should it mean for a complex manifold to be “anti-hyperbolic”? Gromov’s Oka principle is about sufficient geometric conditions for the Oka property to hold. The most important such condition is *ellipticity*, that is, possessing a *dominating spray*, a structure that generalizes the exponential map of a complex Lie group [16, Section 0.5]. For more background, see the monograph [14] and the survey [15].

One of the central problems of Oka theory is to determine the place of Oka manifolds in the classification of compact complex manifolds. This is well understood only for manifolds of dimension 1: a Riemann surface (whether compact or not) is Oka if and only if it is not Kobayashi hyperbolic, and this holds if and only if its universal covering space is not the disk. In particular, the compact Riemann surfaces that are Oka are the Riemann sphere and all elliptic curves. Already for complex surfaces, the problem is difficult and to a large extent open. Whether the Oka property is preserved by blowing up and blowing down is a closely related problem, also difficult and very much open. In particular, we do not know whether an arbitrary Oka manifold blown up at a point is still Oka. This paper is a contribution toward a solution to these two problems.

We will be concerned with several properties of complex manifolds that are (at least ostensibly) weaker than the Oka property.

Definition 1. Let X be a complex manifold (here always taken to be connected).

- (a) X is *stratified Oka* if it admits a stratification $X = X_0 \supset X_1 \supset \cdots \supset X_m = \emptyset$ by closed complex subvarieties, such that every connected component (stratum) of each difference $X_{j-1} \setminus X_j$, $j = 1, \dots, m$, is an Oka manifold.
- (b) X is *dominable at a point* $x \in X$ (by \mathbb{C}^n , where $n = \dim X$) if there is a holomorphic map $f: \mathbb{C}^n \rightarrow X$ such that $f(0) = x$ and f is a local biholomorphism at 0.
- (c) X is *dominable* if it is dominable at some point.

- (d) X is *strongly dominable* if it is dominable at every point.
- (e) X is \mathbb{C} -*connected* if any two points in X can be joined by a finite chain of entire curves in X (this definition has several variants: see Remark 10).
- (f) X is *strongly Liouville* if the universal covering space of X carries no non-constant negative plurisubharmonic functions. \square

Properties (a), (c), (d), and (e) are anti-hyperbolic in the sense that the only Kobayashi hyperbolic manifold satisfying any of them is the point. (For the weakest property (f), this fails. A simply connected, compact, Kobayashi hyperbolic manifold, such as a smooth Kobayashi hyperbolic surface in \mathbb{P}_3 , satisfies (f).) We refer to these properties, the Oka property, ellipticity, and other similar properties, as *holomorphic flexibility* properties to contrast them with the rigidity that characterizes hyperbolicity. (A more specific definition of flexibility exists in the literature [14, Definition 5.5.16], but we shall not use it here.)

An Oka manifold is obviously stratified Oka; the converse is open. The following implications are easily verified.

- (1) If X is Oka, then X is strongly dominable.
- (2) If X is strongly dominable, then X is \mathbb{C} -connected.
- (3) If X is stratified Oka, then X is dominable.
- (4) If X is either dominable or \mathbb{C} -connected, then X is strongly Liouville.

The last implication depends on the well-known fact that \mathbb{C}^n carries no nonconstant negative plurisubharmonic functions. It follows in particular that a manifold that is not strongly Liouville is also not Oka, an observation that will be used in the sequel.

The first main result of the paper is the following theorem.

Theorem 2. A stratified Oka manifold is strongly dominable. \square

A Kummer surface X admits a stratification $X \supset C \supset \emptyset$, where C is the union of 16 mutually disjoint, smooth, rational curves, and the difference $X \setminus C$ is an Oka manifold (Lemma 7). Thus, X is stratified Oka, and we obtain the following corollary.

Corollary 3. Every Kummer surface is strongly dominable. \square

Kummer surfaces are dense in the moduli space of all K3 surfaces, but we do not know whether it follows that all K3 surfaces are strongly dominable. In fact, we prove that strong dominability is in general not closed in families of compact complex manifolds (Corollary 5).

Class VII in the Enriques–Kodaira classification comprises the nonalgebraic compact complex surfaces of Kodaira dimension $\kappa = -\infty$. Minimal surfaces of class VII fall into several mutually disjoint classes. For second Betti number $b_2 = 0$, we have Hopf surfaces and Inoue surfaces. For $b_2 \geq 1$, there are Enoki surfaces, Inoue–Hirzebruch surfaces, and intermediate surfaces; together they form the class of Kato surfaces. By the *global spherical shell conjecture*, currently proved only for $b_2 = 1$ by Teleman [27], every minimal surface of class VII with $b_2 \geq 1$ is a Kato surface. Assuming that the conjecture holds, we determine which minimal surfaces of class VII are Oka.

Theorem 4. Minimal Hopf surfaces and Enoki surfaces are Oka. Inoue surfaces, Inoue–Hirzebruch surfaces, and intermediate surfaces, minimal or blown-up, are not strongly Liouville, and hence not Oka. \square

Enoki surfaces are generic among Kato surfaces. Inoue–Hirzebruch surfaces and intermediate surfaces can be obtained as degenerations of Enoki surfaces (explicit examples are given in [6]). Thus, Theorem 4 yields the following corollary.

Corollary 5. Compact complex surfaces that are Oka can degenerate to a surface that is not strongly Liouville. Consequently, the following properties are in general not closed in families of compact complex manifolds.

- (1) The Oka property.
- (2) The stratified Oka property.
- (3) Strong dominability.
- (4) Dominability.
- (5) \mathbb{C} -connectedness.
- (6) Strong Liouviliness. \square

The corollary answers a question posed in [21]. There it was shown that the Oka fibers in a family of compact complex manifolds form a G_δ set. The corollary says that the set need not be closed. In fact, the corollary suggests that the only interesting closed anti-hyperbolicity property is the weakest anti-hyperbolicity property, the property of not being Kobayashi hyperbolic. Now the open question is whether the set of Oka fibers in a family is open, that is, whether the Oka property is stable under small deformations.

Here is what we know about which minimal compact complex surfaces are Oka.

- (1) $\kappa = -\infty$: Rational surfaces are Oka. A ruled surface is Oka if and only if its base is Oka. Theorem 4 covers class VII if the global spherical shell conjecture is true.
- (2) $\kappa = 0$: Bielliptic surfaces, Kodaira surfaces, and tori are Oka. It is unknown whether any or all K3 surfaces or Enriques surfaces are Oka.
- (3) $\kappa = 1$: Buzzard and Lu determined which properly elliptic surfaces are dominable [3]. Nothing further is known about the Oka property for these surfaces.
- (4) $\kappa = 2$: Surfaces of general type are not dominable (this is an easy consequence of [19, Theorem 2]), and hence not Oka.

In the final section, we show that, often, something survives of the Oka property when an Oka manifold is blown down (Theorem 11). We also establish a perhaps surprising consequence of the hypothesis that the Oka property is preserved by blow-ups, which may suggest that the hypothesis is false (Proposition 12).

2 Stratified Oka Manifolds are Strongly Dominable

In this section, we prove Theorem 2. The proof is based on the following result, which is a special case of [14, Theorem 7.6.1].

Theorem 6. Let X be a Stein manifold, Y be a complex manifold, Y' be a closed complex subvariety of Y , and $f: X \rightarrow Y$ be a continuous map that is holomorphic on an open neighborhood of the preimage $X' = f^{-1}(Y')$ in X . If $Y \setminus Y'$ is an Oka manifold, then, for each $k \geq 1$, there exists a homotopy of continuous maps $f_t: X \rightarrow Y$, $t \in [0, 1]$, such that $f = f_0$, f_1 is holomorphic on X , and for each $t \in [0, 1]$, f_t is holomorphic near X' , agrees with $f = f_0$ to order k along X' , and maps $X \setminus X'$ into $Y \setminus Y'$, that is, $f_t^{-1}(Y') = X'$. \square

Note that $X' = f^{-1}(Y')$ is a closed complex subvariety of X since f is assumed to be holomorphic on a neighborhood of X' .

The special case of Theorem 6 when $Y' = \{0\} \subset \mathbb{C}^d = Y$ follows from classical Oka–Grauert theory since in this case $Y \setminus Y' = \mathbb{C}^d \setminus \{0\}$ is complex homogeneous; it corresponds to the problem of *complete intersections* (see [14, Section 7.5]). The general case, similar to the one stated here, was first proved in [10, Theorem 1.3]. The proof of the general case is explained in [14, Section 7.6], and is based on the paper [13].

Proof of Theorem 2. Let Y be a stratified Oka manifold of dimension n and let $Y = Y_0 \supset Y_1 \supset \dots \supset Y_l = \emptyset$ be a stratification of Y such that $S_j = Y_j \setminus Y_{j+1}$ is Oka for $j = 0, \dots, l - 1$. Given a point $y_0 \in Y$, we wish to find a holomorphic map $F : \mathbb{C}^n \rightarrow Y$ such that $F(0) = y_0$ and F is dominating at 0.

If $y_0 \in S_0 = Y_0 \setminus Y_1$, then the Oka property of S_0 implies that there is a holomorphic map $F : \mathbb{C}^n \rightarrow S_0$ with $F(0) = y_0$ and rank n at 0.

Now suppose $y_0 \in S_1 = Y_1 \setminus Y_2$. Let Σ be the connected component of S_1 containing y_0 . Set $m = \dim \Sigma$ and $d = n - m$. Since Σ is Oka by assumption, there is a holomorphic map $g : \mathbb{C}^m \rightarrow \Sigma$ such that $g(0) = y_0$ and g is a local biholomorphism at 0.

We identify \mathbb{C}^m with the subspace $\mathbb{C}^m \times \{0\}^d$ of \mathbb{C}^n . Write the coordinates on \mathbb{C}^n as $z = (z', z'')$ with $z' = (z_1, \dots, z_m)$ and $z'' = (z_{m+1}, \dots, z_n)$. We shall construct a holomorphic map $F : \mathbb{C}^n \rightarrow Y$ such that $F(z', 0) = g(z')$ for all $z' \in \mathbb{C}^m$, F maps $\mathbb{C}^n \setminus (\mathbb{C}^m \times \{0\}^d)$ into S_0 , and F is a local biholomorphism at 0.

Let $N \rightarrow \Sigma$ be the holomorphic normal bundle of Σ in Y . By Grauert’s Oka principle, the pullback $g^*N \rightarrow \mathbb{C}^m$ is a trivial holomorphic vector bundle over \mathbb{C}^m (see [14, Section 7.2]). A trivialization of this bundle is given by d linearly independent holomorphic vector fields V_1, \dots, V_d on Y along g that are normal to Σ . More precisely, for every point $z' \in \mathbb{C}^m$ and its image $w' = g(z') \in \Sigma$, the vectors $V_1(z'), \dots, V_d(z') \in T_{w'}Y$ give a basis of the normal space $N_{w'} = T_{w'}Y / T_{w'}\Sigma$.

The graph

$$G = \{(z', g(z')) : z' \in \mathbb{C}^m\} \subset \mathbb{C}^m \times Y$$

of g is a submanifold of $\mathbb{C}^m \times Y$, biholomorphic to \mathbb{C}^m , so it has a Stein open neighborhood Ω in $\mathbb{C}^m \times Y$ by Siu’s theorem [14, Theorem 3.1.1; 26]. We identify each V_j with a vector field on $\mathbb{C}^m \times Y$, defined along G , that is, tangential to the fibers of the projection $\pi_1 : \mathbb{C}^m \times Y \rightarrow \mathbb{C}^m$. After shrinking Ω around G if necessary, we can assume that V_1, \dots, V_d extend to holomorphic vector fields on Ω that are tangential to the fibers of π_1 . (Since V_1, \dots, V_d are sections of a holomorphic vector bundle, we can also appeal to Cartan’s Theorem B to extend them holomorphically to all of Ω .) Let ϕ_t^j denote the flow of V_j for small complex values of time t (depending on the initial point). Let $\pi_2 : \mathbb{C}^m \times Y \rightarrow Y$ be the projection on to the second factor. The formula

$$f(z', z'') = \pi_2 \circ \phi_{z_{m+1}}^1 \circ \dots \circ \phi_{z_n}^d(z', g(z'))$$

defines a holomorphic map f into Y from an open neighborhood of $\mathbb{C}^m \times \{0\}^d$ in \mathbb{C}^n , such that $f(z', 0'') = g(z')$ for $z' \in \mathbb{C}^m$ and

$$\left. \frac{\partial}{\partial z_j} f(z', z'') \right|_{z''=0} = V_{j-m}(z') \quad \text{for } z' \in \mathbb{C}^m \text{ and } j = m + 1, \dots, n.$$

Hence, the differential $df_{(z,0'')} : T_{(z,0'')} \mathbb{C}^n \rightarrow T_{g(z)} Y$ is an isomorphism for every $z' \in \mathbb{C}^m$ near the origin. In particular, f is dominating at $0 \in \mathbb{C}^n$ and $f(0) = g(0') = y_0$. Furthermore, as the vector fields V_1, \dots, V_d trivialize the normal bundle to Σ in Y , the above implies that there is a neighborhood U of $\mathbb{C}^m \times \{0\}^d$ in \mathbb{C}^n such that

$$f(U \setminus \mathbb{C}^m \times \{0\}^d) \subset S_0 = Y_0 \setminus Y_1.$$

We may contract \mathbb{C}^n into U by a smooth contraction that equals the identity on a smaller open neighborhood $V \subset U$ of $\mathbb{C}^m \times \{0\}^d$. Precomposing f with this contraction yields a continuous map $\mathbb{C}^n \rightarrow Y$ which agrees with f on V and maps $\mathbb{C}^n \setminus (\mathbb{C}^m \times \{0\}^d)$ into S_0 . Theorem 6 now provides an entire map $F : \mathbb{C}^n \rightarrow Y$ which agrees with f to second order along $\mathbb{C}^m \times \{0\}^d$ and maps $\mathbb{C}^n \setminus (\mathbb{C}^m \times \{0\}^d)$ into S_0 . In particular, F is dominating at 0 and $F(0) = y_0$. This completes the proof when $y_0 \in S_1$.

In general, if $y_0 \in S_k = Y_k \setminus Y_{k+1}$ for some $k \in \{1, \dots, l - 1\}$, we choose strata $\Sigma_j \subset S_j$ for $j = 0, \dots, k$ such that $y_0 \in \Sigma_k$ and $\Sigma_j \subset \bar{\Sigma}_{j-1}$ for $j = 1, \dots, k$. Let $m_j = \dim \Sigma_j$, so $m_0 = n > m_1 > \dots > m_k$. Set $d_j = m_j - m_{j+1}$ for $j = 0, \dots, k - 1$. Since Σ_k is Oka, there is an entire map $g_k : \mathbb{C}^{m_k} \rightarrow \Sigma_k$ which sends 0 to y_0 and is dominating at 0. By the above argument and downward induction over $j = 0, \dots, k - 1$, there are entire maps $g_j : \mathbb{C}^{m_j} \rightarrow \Sigma_j$ such that $g_j = g_{j+1}$ on $\mathbb{C}^{m_{j+1}} \times \{0\}^{d_j}$, and g_j is dominating at 0 (as a map into Σ_j). For $j = 0$, we thus get an entire map $F = g_0 : \mathbb{C}^n \rightarrow Y$ which is dominating at 0 with $F(0) = y_0$. ■

3 Kummer Surfaces are Strongly Dominable

In this section, we show that all Kummer surfaces are stratified Oka, and hence strongly dominable by Theorem 2. We also prove a variant of the Oka property for maps of Stein surfaces to Kummer surfaces.

Let us recall the structure of Kummer surfaces (see [1] for more information). Let \mathbb{T} be a complex 2-torus, the quotient of \mathbb{C}^2 by a lattice $\mathbb{Z}^4 \cong \Gamma \subset \mathbb{C}^2$ of rank 4, acting on \mathbb{C}^2 by translations. Let $\pi : \mathbb{C}^2 \rightarrow \mathbb{T} = \mathbb{C}^2/\Gamma$ be the quotient map. The involution $\mathbb{C}^2 \rightarrow \mathbb{C}^2, (z_1, z_2) \mapsto (-z_1, -z_2)$, descends to an involution $\sigma : \mathbb{T} \rightarrow \mathbb{T}$ with precisely 16 fixed points p_1, \dots, p_{16} . In fact, if $\omega_1, \dots, \omega_4 \in \mathbb{C}^2$ are generators for Γ , then p_1, \dots, p_{16} are the

images under π of the 16 points $c_1\omega_1 + \dots + c_4\omega_4$, where $c_1, \dots, c_4 \in \{0, \frac{1}{2}\}$. The quotient space $\mathbb{T}/\{1, \sigma\}$ is a two-dimensional complex space with 16 singular points q_1, \dots, q_{16} . The singularities can be resolved by blowing up q_1, \dots, q_{16} , yielding a smooth compact surface Y containing 16 mutually disjoint smooth rational curves C_1, \dots, C_{16} . This is the Kummer surface associated to the torus \mathbb{T} or to the lattice Γ .

Here is an alternative description. Let X denote the surface obtained by blowing up the torus \mathbb{T} at each of the 16 points p_1, \dots, p_{16} . Let $E_j \cong \mathbb{P}_1$ denote the exceptional divisor over p_j . The involution σ of \mathbb{T} lifts to an involution $\tau : X \rightarrow X$ with the fixed point set $E = E_1 \cup \dots \cup E_{16}$. The eigenvalues of the differential $d\tau$ at any point of E are 1 and -1 . Hence, the quotient $X/\{1, \tau\}$ is smooth and contains 16 rational (-2) -curves $C_j \cong \mathbb{P}_1$, the images of the rational (-1) -curves E_j in X . The quotient is the Kummer surface Y . Denoting by $\hat{\mathbb{C}}^2$ the surface obtained by blowing up \mathbb{C}^2 at every point of the discrete set $\tilde{\Gamma} = \pi^{-1}(\{p_1, \dots, p_{16}\})$, we have the following diagram (see [1, p. 224]):

$$\begin{array}{ccccc}
 \hat{\mathbb{C}}^2 & \longrightarrow & X & \longrightarrow & Y \\
 \downarrow & & \downarrow & & \downarrow \\
 \mathbb{C}^2 & \xrightarrow{\pi} & \mathbb{T} & \longrightarrow & \mathbb{T}/\{1, \sigma\}
 \end{array}$$

Lemma 7. Let Y be a Kummer surface with the exceptional rational curves C_1, \dots, C_{16} . Then $Y \supset C = C_1 \cup \dots \cup C_{16} \supset \emptyset$ is a stratification whose strata are Oka. □

Proof. Since each curve $C_j \cong \mathbb{P}_1$ is Oka, we only need to prove that $Y \setminus C$ is Oka. To see this, note that the involution $\tau : X \rightarrow X$ acts without fixed points on $X \setminus E$, so $X \setminus E$ is an unbranched, double-sheeted, covering space of $Y \setminus C$. Now $X \setminus E$ is universally covered by $\mathbb{C}^2 \setminus \tilde{\Gamma}$. Buzzard and Lu [3, Proposition 4.1] showed that the discrete set $\tilde{\Gamma}$ is tame in \mathbb{C}^2 in the sense of Rosay and Rudin [25] (see also [14, Section 4.6]). Hence, $\mathbb{C}^2 \setminus \tilde{\Gamma}$ is Oka [14, Proposition 5.5.14]. Since the Oka property passes down along unbranched holomorphic covering maps [14, Proposition 5.5.2], $X \setminus E$ and $Y \setminus C$ are also Oka. ■

The surface X obtained by blowing up a 2-torus at finitely many points is Oka [14, Corollary 6.4.12]. We do not know whether its quotient Y is also Oka; the problem is that the quotient map $X \rightarrow Y$ is branched, and it is unknown whether the Oka property passes down along finite branched covering maps. However, the strong dominability of X obviously passes down to give the dominability of Y at each point of $Y \setminus C$. Since the

projection $X \rightarrow Y$ is branched over C , holomorphic maps $\mathbb{C}^2 \rightarrow Y$ dominating at points of C , which exist by Corollary 3, do not factor through X .

It would be interesting to know whether every Kummer surface Y satisfies the Oka property restricted to maps from Stein surfaces to Y . By inspecting the proof of Theorem 2, we see that the problem is essentially topological. Therefore, it is not surprising that we have a positive result for Stein surfaces with sufficiently simple topology, that is, for the *subcritical* Stein surfaces whose CW-decomposition does not contain any cells of index 2.

Theorem 8. Let Y be a Kummer surface with the rational curves $C = C_1 \cup \cdots \cup C_{16}$. Let S be a Stein surface and Σ be a smooth, possibly disconnected, complex curve in S . If S is obtained from Σ by adding only cells of index 0 or 1, then every holomorphic map $f: \Sigma \rightarrow C$ extends to a holomorphic map $F: S \rightarrow Y$ such that $F(S \setminus \Sigma) \subset Y \setminus C$. If f is dominating (of rank 1) at some point $x \in \Sigma$, then the extension F can be chosen to be dominating (of rank 2) at x . \square

Proof. By following the proof of Theorem 2, we can extend f to a holomorphic map $U \rightarrow Y$ from an open tubular neighborhood U of Σ in S such that $f(U \setminus \Sigma) \subset Y \setminus C$. Furthermore, the extension can be chosen such that its rank at any point $x \in \Sigma$ equals the rank of $f|_{\Sigma}$ plus 1. (It is important to observe that the normal bundle of a noncompact, smooth, complex curve is trivial. Indeed, any holomorphic vector bundle on an open Riemann surface is trivial by the Oka–Grauert principle; see [14, Theorem 5.3.1].) Since $Y \setminus C$ is connected, the topological assumption on the pair (S, Σ) implies that f extends to a continuous map $S \rightarrow Y$ taking $S \setminus \Sigma$ to $Y \setminus C$. Since $Y \setminus C$ is Oka by Lemma 7, Theorem 6 enables us to deform f to a holomorphic map $F: S \rightarrow Y$, which agrees with f to second order along Σ and maps $S \setminus \Sigma$ to $Y \setminus C$.

However, since $Y \setminus C$ is not simply connected, it may be impossible to extend f across cells of index 2 in a relative CW-complex representing the pair (S, Σ) . Indeed, if the restriction of the given map to the boundary of a cell of index 2 represents a nontrivial loop in $Y \setminus C$, then the map cannot be extended across the cell (as a map into $Y \setminus C$). \blacksquare

Example 9. The surface $S = \mathbb{C}^2$ with Σ equal to the union of finitely many, mutually disjoint, affine complex lines $\Sigma_1, \dots, \Sigma_m$ satisfies the hypothesis of Theorem 8. Hence, there is a dominating holomorphic map $\mathbb{C}^2 \rightarrow Y$ whose restriction to each Σ_j equals

any prescribed biholomorphism on to the complement of a chosen point in any of the rational curves C_1, \dots, C_{16} . □

4 Oka Surfaces of Class VII

In this section, we prove Theorem 4 by considering each of the five classes of minimal surfaces X of class VII in turn.

If X is Hopf, then the universal covering space of X is $\mathbb{C}^2 \setminus \{0\}$, which is Oka, so X is Oka.

If X is Inoue, then the universal covering space of X is $\mathbb{D} \times \mathbb{C}$, where \mathbb{D} denotes the open disk, which clearly carries a nonconstant, negative, plurisubharmonic function. Hence, an Inoue surface is not strongly Liouville.

If X is intermediate, then X is not strongly Liouville by Dloussky and Oeljeklaus [7, Corollary 2.13].

Let X be Inoue–Hirzebruch and D be the union of the finitely many rational curves in X . Let \tilde{D} be the preimage of D in the universal covering space \tilde{X} of X . The complement $\tilde{X} \setminus \tilde{D}$ is described in [7, Proof of Theorem 2.16], and in [28, pp. 400–401]. In the notation of [7], $\tilde{X} \setminus \tilde{D}$ is isomorphic to the image by the map $\mathbb{C} \times \mathbb{C} \rightarrow \mathbb{C}^* \times \mathbb{C}^*$, $(\zeta_1, \zeta_2) \mapsto (e^{\zeta_1}, e^{\zeta_2})$, of the half-space in $\mathbb{C} \times \mathbb{C}$ defined by the inequality $-d\operatorname{Re}\zeta_1 + c\operatorname{Re}\zeta_2 < 0$, where $d < 0 < c$. Thus, $-d\log|z_1| + c\log|z_2|$ defines a nonconstant negative plurisubharmonic function on $\tilde{X} \setminus \tilde{D}$, which extends across \tilde{D} to a plurisubharmonic function on \tilde{X} , so X is not strongly Liouville.

It is easily seen that not being strongly Liouville is preserved by blowing up. It follows that blown-up Inoue, Inoue–Hirzebruch, and intermediate surfaces are not strongly Liouville.

By Enoki’s original construction of the surfaces that now bear his name [8, 9, Section 3], the universal covering space Y of an Enoki surface X is obtained as follows. Let $W_0 = \mathbb{P}_1 \times \mathbb{C}$ and $\Gamma = \{\infty\} \times \mathbb{C} \subset W_0$. For each $k \geq 0$, W_{k+1} is W_k blown up at two distinct points p_k and p_{-k-1} , such that, when $k \geq 1$, p_k lies in the total transform of p_{k-1} , and p_{-k-1} lies in the total transform of p_{-k} . We take $p_0 = (\infty, 0)$ and $p_{-1} = (a, 0)$ with $a \in \mathbb{C}$. Also, p_k lies in the proper transform Γ_k of Γ , but p_{-k-1} lies outside the total transform of Γ . (We interpret the proper transform and the total transform of Γ in W_0 as Γ itself.) Then p_{-1}, p_{-2}, \dots lie in the total transforms of the line $\{a\} \times \mathbb{C}$. Let $Y_k = W_k \setminus (\Gamma_k \cup \{p_{-k-1}\})$. Then Y_k may be viewed as an open subset of Y_{k+1} and Y is the colimit of the sequence $Y_0 \subset Y_1 \subset Y_2 \subset \dots$. (There is a misprint on [9, p. 459]: the total transform of p_{-k-1} is C_{-k-1} , not C_{-k-2} .)

If we formulate the Oka property as the convex approximation property, it is evident that if Y_k is Oka for all $k \geq 0$, then Y is Oka, so X is Oka [14, Proposition 5.5.6]. We claim that $W_k \setminus \Gamma_k$ is Zariski-locally affine (affine meaning algebraically isomorphic to \mathbb{C}^2); then Y_k is Oka [14, Proposition 6.4.6].

Being Zariski-locally affine is preserved by blowing up points [14, Proposition 6.4.7; 16, Section 3.5.D"]. Since $W_0 \setminus \Gamma = \mathbb{C} \times \mathbb{C}$ is affine, the complement in W_k of the total transform of Γ is Zariski-locally affine. Thus, we need to show that every point in $W_{k+1} \setminus \Gamma_{k+1}$, $k \geq 0$, that lies in the total transform of Γ has an affine Zariski-open neighborhood in $W_{k+1} \setminus \Gamma_{k+1}$.

We claim that every point in W_k , $k \geq 0$, that lies in the total transform of Γ has an affine Zariski-open neighborhood U in W_k containing p_k but not p_{-k-1} , in which Γ_k appears as a straight line. Namely, for $k=0$, let $U = (\mathbb{P}_1 \setminus \{a\}) \times \mathbb{C}$. Suppose that the claim is true for k and let $w \in W_{k+1}$ lie in the total transform of Γ . Let V be an affine Zariski-open neighborhood of the image of w in W_k containing p_k but not p_{-k-1} , in which Γ_k appears as a straight line. Blowing up V at p_k yields a Zariski-open neighborhood V' of w in W_{k+1} . Take a line L in V through p_k different from Γ_k , whose proper transform L' contains neither w nor p_{k+1} , and set $U = V' \setminus L'$. Then U is a Zariski-open neighborhood of w in W_{k+1} containing p_{k+1} but not p_{-k-2} . Moreover, U is algebraically isomorphic to the total space of an algebraic line bundle over \mathbb{C} , so U is affine, and Γ_{k+1} appears as a straight line in U .

Finally, let $w \in W_{k+1} \setminus \Gamma_{k+1}$, $k \geq 0$, lie in the total transform of Γ . Let U be an affine Zariski-open neighborhood of the image of w in W_k containing p_k but not p_{-k-1} , in which Γ_k appears as a straight line. Blowing up U at p_k and removing the proper transform of Γ_k yields an affine Zariski-open neighborhood of w in $W_{k+1} \setminus \Gamma_{k+1}$.

This shows that minimal Enoki surfaces are Oka, so Theorem 4 is proved.

5 The Oka Property is not Closed in Families

Corollary 5 follows from Theorem 4 because there is a family $\pi : Y \rightarrow \mathbb{D}$ of compact complex manifolds, that is, a proper holomorphic submersion and thus a smooth fiber bundle, such that the central fiber $\pi^{-1}(0)$ is an Inoue–Hirzebruch surface or an intermediate surface, and the other fibers $\pi^{-1}(t)$, $t \in \mathbb{D} \setminus \{0\}$, are minimal Enoki surfaces. See, for instance, the explicit examples on [6, pp. 34–35].

Corollary 5 implies that the Brody reparameterization lemma that is used to show that Kobayashi hyperbolicity is open in families of compact complex manifolds [2] has no higher-dimensional version that could be used to similarly prove that being

the target of a nondegenerate holomorphic map from \mathbb{C}^2 is closed in families. (A weaker higher-dimensional version of the reparameterization lemma was proved in [23].)

Remark 10. A remark on the definition of \mathbb{C} -connectedness is in order. It is not a well-known or much-studied property. Gromov defined a complex manifold X to be \mathbb{C} -connected if any two points of X lie in the image of a holomorphic map $\mathbb{C} \rightarrow X$, that is, in an entire curve [16, Section 3.4]. We chose a weaker property in Definition 1. There are obvious alternatives, ranging from requiring every finite subset of X to lie in an entire curve (this holds if X is connected and Oka) to requiring that any two general points can be joined by a chain of entire curves. We do not know whether these definitions are equivalent, but Corollary 5 clearly holds for all of them. It is of interest to compare \mathbb{C} -connectedness with rational connectedness, a well-understood property introduced in [4, 20]. For a smooth proper algebraic variety, the four definitions we have mentioned, with entire curves replaced by rational curves, are equivalent [20, 2.1, 2.2]. Rational connectedness is deformation-invariant [20, 2.4], but by Corollary 5, the \mathbb{C} -connectedness of compact complex manifolds is not.

In the context of \mathbb{C} -connectedness, we mention that Campana has introduced the notion of a compact Kähler manifold X being *special* [5]. It is an anti-hyperbolicity or anti-general type notion. Campana has proved that X is special if X is either dominable, rationally connected, or has Kodaira dimension 0. On the other hand, if X is of general type, then X is not special. Campana has conjectured that X is special if and only if X is \mathbb{C} -connected if and only if the Kobayashi pseudo-metric of X vanishes identically. \square

6 Blowing an Oka Manifold Up or Down

It is an open problem whether a blow-down of an Oka manifold is still Oka. In this section, we prove the following partial result in this direction.

Theorem 11. Let E be a discrete subset of a complex manifold X and let \tilde{X} be X blown up at each point of E . Suppose that \tilde{X} has one of the following properties:

- (a) \tilde{X} is an Oka manifold, and global holomorphic vector fields on \tilde{X} span the tangent space of \tilde{X} at each point;
- (b) \tilde{X} is elliptic in the sense of Gromov (see [16, Section 0.5]).

Then X has the basic Oka property with approximation for maps $S \rightarrow X$ from Stein manifolds S with $\dim S \leq \dim X$. \square

The conclusion of the theorem means the following. Given a Stein manifold S of dimension at most $n = \dim X$, a holomorphically convex compact set K in S , and a continuous map $f: S \rightarrow X$ that is holomorphic on an open neighborhood U of K in S , it is possible to deform f to a holomorphic map $f_1: S \rightarrow X$ through continuous maps $f_t: S \rightarrow X$, $t \in [0, 1]$, that are holomorphic on an open set containing K and are uniformly as close as desired to the initial map $f = f_0$ on K .

We recall that every elliptic manifold is Oka [14, Corollary 5.5.12]. Note that we take a discrete subset to be closed by definition.

Proof. Assume first that $\dim S < n$. Pick a compact, holomorphically convex set K in S and a continuous map $f: S \rightarrow X$ that is holomorphic on an open neighborhood U of K in S . Choose a smaller open neighborhood $U_1 \Subset U$ of K . By the transversality theorem of Kaliman and Zaidenberg [18] (see also [14, Section 7.8]), there exists a holomorphic map $\tilde{f}: U_1 \rightarrow X$, close to $f|_{U_1}$, that is, transverse to the discrete set $E \subset X$, and hence by dimension reasons it avoids E . Assuming as we may that \tilde{f} is close enough to f on U_1 , and shrinking U_1 around K if necessary, we conclude that $\tilde{f}|_{U_1}$ is also homotopic to $f|_{U_1}$ through a homotopy of holomorphic maps. By using a cut-off function in the parameter of the homotopy and the usual transversality theorem for smooth maps, we can extend \tilde{f} , without changing its values on a smaller neighborhood $U_2 \Subset U_1$ of K , to a smooth map $\tilde{f}: S \rightarrow X \setminus E$ that is holomorphic in a neighborhood U_2 of K . Hence, \tilde{f} lifts to a continuous map $g: S \rightarrow \tilde{X}$ that is holomorphic near K . Since \tilde{X} is Oka, we can deform g to a holomorphic map $S \rightarrow \tilde{X}$ which approximates g uniformly on K . By pushing the homotopy down to X , we get a deformation of \tilde{f} , and hence of f , to a holomorphic map $f_1: S \rightarrow X$.

Suppose now that $\dim S = n$. By the same perturbation argument as above, we may assume that the restriction $f|_U: U \rightarrow X$ to an open neighborhood U of K in S is transverse to the discrete set $E \subset X$. Equivalently, every point of E is a regular value of $f|_U$. This implies that the set $U \cap f^{-1}(E)$ is discrete, and after shrinking U slightly around K , we may assume that it is finite.

Choose a strongly plurisubharmonic Morse exhaustion function $\rho: S \rightarrow \mathbb{R}$ such that $K \subset \{\rho < 0\} \Subset U$ and 0 is a regular value of ρ . Then S is a cellular extension of the compact set $L = \{\rho \leq 0\}$, obtained by attaching to L cells of index at most n .

Write $f^{-1}(E) \cap L = \{p_1, p_2, \dots, p_m\}$. By standard topological arguments, we can deform f , keeping it fixed on L , to a new map $\tilde{f}: S \rightarrow X$ such that $\tilde{f}^{-1}(E) = \{p_1, p_2, \dots, p_m\} \subset L$. In fact, suppose that such a deformation has already been found over the sublevel set $\{\rho \leq t\}$ for some $t \geq 0$, and we wish to extend it to $\{\rho \leq t'\}$ for some

$t' > t$. We may assume that t and t' are regular values of ρ . If ρ has no critical values in $[t, t']$, there is no change of topology, so the extension obviously exists. At a critical point of ρ , we need to choose the extension of the deformation across a totally real disk of dimension equal to the Morse index of ρ such that the range of the new map avoids E . Since the real dimension of any such disk is at most n , the desired property can be achieved by a general position argument. Thus, replacing f by \tilde{f} , we may assume that $f^{-1}(E) = \{p_1, p_2, \dots, p_m\} \subset L$.

Let \tilde{S} be obtained by blowing up S at each of the points p_1, \dots, p_m , and let $\tau : \tilde{S} \rightarrow S$ be the blow-down map. Then \tilde{S} is a 1-convex manifold with the exceptional divisors $\Lambda_j \cong \mathbb{P}_{n-1}$ over the points p_j , and the map τ is the Remmert reduction of \tilde{S} . Similarly, we denote by $\pi : \tilde{X} \rightarrow X$ the blow-down map which collapses each of the exceptional divisors over the points of E . Note that the restrictions $\pi : \tilde{X} \setminus \pi^{-1}(E) \rightarrow X \setminus E$ and $\tau : \tilde{S} \setminus \Lambda \rightarrow S \setminus \{p_1, \dots, p_m\}$, where $\Lambda = \Lambda_1 \cup \dots \cup \Lambda_m$, are biholomorphic.

Since f is locally biholomorphic near each of the points p_1, \dots, p_m , it induces a holomorphic map $g : \tilde{S} \rightarrow \tilde{X}$ such that the following diagram commutes:

$$\begin{array}{ccc}
 \tilde{S} & \xrightarrow{g} & \tilde{X} \\
 \tau \downarrow & & \downarrow \pi \\
 S & \xrightarrow{f} & X
 \end{array}$$

The map g is holomorphic on a neighborhood of $\tilde{L} = \tau^{-1}(L)$ in \tilde{S} and maps each divisor Λ_j biholomorphically on to the exceptional divisor $E_j = \pi^{-1}(f(p_j)) \subset \tilde{X}$ over the image point $f(p_j) \in E$. Furthermore, since f maps $S \setminus \{p_1, \dots, p_m\}$ to $X \setminus E$, its lifting g maps $\tilde{S} \setminus \Lambda$ to $\tilde{X} \setminus \pi^{-1}(E)$.

Since the manifold \tilde{S} is 1-convex, Theorem A.1 in the Appendix shows that the Oka principle applies to maps $\tilde{S} \rightarrow \tilde{X}$ that are holomorphic near the exceptional subvariety Λ of \tilde{S} , with interpolation to any given finite order along Λ , and with approximation on the holomorphically convex compact set $\tilde{L} = \tau^{-1}(L) \subset \tilde{S}$. We thus obtain a holomorphic map $g_1 : \tilde{S} \rightarrow \tilde{X}$, homotopic to g , that agrees with g to second order along Λ . Hence, g_1 descends to a holomorphic map $f_1 : S \rightarrow X$: this is nontrivial only over a neighborhood of the finite set $\{p_1, \dots, p_m\}$ in S that was blown up; elsewhere, we get f_1 simply by noting that the restriction $\tau : \tilde{S} \setminus \Lambda \rightarrow S \setminus \{p_1, \dots, p_m\}$ is biholomorphic. ■

Our next result presents a consequence of the hypothesis that the Oka property is preserved by blow-ups. It may point to the hypothesis being false. The first question

to consider would be whether every embedded disk in \mathbb{C}^3 is a holomorphic retract of an embedded surface.

Proposition 12. Let A be a submanifold of \mathbb{C}^n , contractible and not Oka. If the blow-up of \mathbb{C}^n along A is Oka, then A is a holomorphic retract of a hypersurface in \mathbb{C}^n . \square

Proof. Let B be the blow-up of \mathbb{C}^n along A with the projection $\pi : B \rightarrow \mathbb{C}^n$. The restriction $\pi : L = \pi^{-1}(A) \rightarrow A$ is the projectivized normal bundle of A and L is a smooth hypersurface in B .

Since A is contractible and Stein, its normal bundle is holomorphically trivial by the Oka–Grauert principle [14, Section 5.3], so the restriction $\pi : L \rightarrow A$ admits a holomorphic section $\sigma : A \rightarrow L$. Since A and \mathbb{C}^n are both contractible, the inclusion $A \hookrightarrow \mathbb{C}^n$ is an acyclic cofibration, so $A \xrightarrow{\sigma} L \hookrightarrow B$ extends to a continuous map $\tau : \mathbb{C}^n \rightarrow B$. (Readers unfamiliar with the basic homotopy theory result invoked here may consult [22]: it follows from the proposition on p. 44 that A is a continuous retract of \mathbb{C}^n .) Furthermore, as B is Oka by assumption, we can choose the extension τ to be holomorphic. (Note that in the case of interest, when $\dim A \leq n - 2$, τ is not a section of $\pi : B \rightarrow \mathbb{C}^n$, as π has no continuous sections at all.)

The preimage $H = \tau^{-1}(L) \subset \mathbb{C}^n$ is either all of \mathbb{C}^n or a (possibly singular) hypersurface in \mathbb{C}^n . Let $\rho = \pi \circ \tau : H \rightarrow A$. Then $A \subset H$ and $\rho|_A = \pi \circ \sigma = \text{id}_A$, so ρ is a holomorphic retraction of H on to A . Now a holomorphic retract of an Oka manifold is Oka, and so since A is not Oka, H is not \mathbb{C}^n . \blacksquare

Remark 13. By a more involved construction, it is possible to insure that the hypersurface in Proposition 12 is smooth (and drop the hypothesis that A is not Oka). Here is an outline; we leave the details to the reader.

Using the notation in the proof of the proposition, let N be the normal (line) bundle of the smooth hypersurface $L = \pi^{-1}(A)$ in B . Choose a holomorphic section $\sigma : A \rightarrow L$ as in the proof. Since A is contractible, the restriction of the line bundle N to the submanifold $\sigma(A) \subset L$ is holomorphically trivial, and thus admits a nowhere-vanishing holomorphic section W . The normal bundle of A in \mathbb{C}^n is also trivial, so it admits a nowhere-vanishing holomorphic section V . We can view V as a holomorphic vector field on \mathbb{C}^n along A . Using the techniques in [14, Section 3.4], we can extend $\sigma : A \rightarrow L$ to a holomorphic map $\tilde{\sigma} : U \rightarrow B$ on an open neighborhood U of A in \mathbb{C}^n , such that its differential $d\tilde{\sigma}$ at any point of A maps V to W . This implies that $\tilde{\sigma}$ is transverse to L in some open neighborhood $U' \subset U$ of A . By the same argument as above, using the Oka

principle for maps $\mathbb{C}^n \rightarrow B$, we can interpolate $\tilde{\sigma}$ to second order along A by a holomorphic map $\tau : \mathbb{C}^n \rightarrow B$ that is everywhere transverse to the hypersurface L (see [14, Section 7.8]). It follows that the preimage $H = \tau^{-1}(L)$ is a smooth hypersurface in \mathbb{C}^n , and A is a holomorphic retract of H . □

Finally, in case the reader is wondering what happens to Proposition 12 when A is Oka, we offer the following result.

Proposition 14. A contractible complex submanifold A of \mathbb{C}^n is Oka if and only if A is a holomorphic deformation retract of \mathbb{C}^n itself. □

It is immaterial here whether or not the blow-up of \mathbb{C}^n along A is Oka.

It follows that every holomorphically embedded complex line L in \mathbb{C}^n , $n \geq 2$, is a holomorphic deformation retract of \mathbb{C}^n , although L need not be straightenable. It is even possible that $\mathbb{C}^n \setminus L$ is Kobayashi hyperbolic (see [14, Section 4.18]).

Proof. First, if A is a holomorphic retract of \mathbb{C}^n , then A is Oka. Now suppose that A is Oka. Since A is also contractible, the identity map of A extends by the inclusion $A \hookrightarrow \mathbb{C}^n$ to a holomorphic retraction $\rho : \mathbb{C}^n \rightarrow A$.

Let $W = (\mathbb{C}^n \times \{0, 1\}) \cup (A \times [0, 1])$ and define a continuous map $f : W \rightarrow \mathbb{C}^n$ by $f(x, 0) = x$ and $f(x, 1) = \rho(x)$ if $x \in \mathbb{C}^n$, and $f(a, t) = a$ if $a \in A$ and $t \in [0, 1]$. Since $W \hookrightarrow \mathbb{C}^n \times [0, 1]$ is a cofibration and \mathbb{C}^n is contractible, f extends to a continuous map $g : \mathbb{C}^n \times [0, 1] \rightarrow \mathbb{C}^n$. Since \mathbb{C}^n is Oka, we can use the parametric Oka principle [14, Theorem 5.4.4] to deform g , keeping it fixed on W , to a continuous map h such that $h(\cdot, t) : \mathbb{C}^n \rightarrow \mathbb{C}^n$ is holomorphic for all $t \in [0, 1]$. This shows that A is a holomorphic deformation retract of \mathbb{C}^n . ■

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Appendix: The Oka principle for maps from 1-convex manifolds

In this appendix, we sketch the proof of the following result which was used in the proof of Theorem 11.

Recall that a complex manifold S is said to be 1-convex if S admits an exhaustion function that is strongly plurisubharmonic outside a compact subset of S . Such a

manifold S contains a maximal compact complex subvariety Λ of positive dimension (possibly empty). The Remmert reduction of S , which is obtained by blowing down each connected component of Λ to a point, is a (possibly singular) Stein space.

Theorem A.1. Let X be a complex manifold with one of the following properties:

- (a) X is an Oka manifold, and holomorphic vector fields on X span the tangent space of X at each point;
- (b) X is elliptic in the sense of Gromov (see [16, Section 0.5]).

Given a 1-convex manifold S with the exceptional variety Λ , a compact holomorphically convex subset L of S , and a continuous map $f: S \rightarrow X$ which is holomorphic in a neighborhood of $\Lambda \cup L$, there is a holomorphic map $\tilde{f}: S \rightarrow X$ that agrees with f to a given finite order along Λ and uniformly approximates f as closely as desired on L . The map \tilde{f} can be chosen to be homotopic to f through a homotopy of maps that are holomorphic near $\Lambda \cup L$, agree with f to a given finite order along Λ , and uniformly approximate f on L . \square

This *relative Oka principle* is due to Henkin and Leiterer [17] in the classical case when X is complex homogeneous.

In [24], Prezelj stated a much more general Oka principle for sections of holomorphic submersions $Z \rightarrow S$ on to 1-convex manifolds S . A map $S \rightarrow X$ can be identified with a section of the trivial submersion $Z = S \times X \rightarrow S$, and in this case the only hypothesis in her result [24, Theorem 1.1] is that the fiber X of the submersion is an Oka manifold. However, there is a gap in the proof given in [24], and it is not clear at this time whether the proof can be repaired. The (only) problem lies in the construction of a local dominating holomorphic spray around a given holomorphic section $f: S \rightarrow Z$ (see [24, Section 4.2]). We lack a proof that there exist vertical holomorphic vector fields in certain conical Stein neighborhoods of the graph $f(S \setminus \Lambda) \subset Z$ that are bounded near $f(\Lambda)$ (here, $\Lambda \subset S$ is the exceptional variety) and that generate the vertical tangent bundle of Z . In the special case of interest to us, the proof in [24] is correct and complete provided, that X is an Oka manifold satisfying the following additional property.

Property ELS (existence of local sprays). A complex manifold X satisfies ELS if, for every holomorphic map $f: S \rightarrow X$ from a 1-convex manifold S and every relatively compact open set $U \Subset S$ containing the exceptional variety Λ of S , there exist an integer $N \in \mathbb{N}$,

an open set $V \subset \mathbb{C}^N$ with $0 \in V$, and a holomorphic map $F : U \times V \rightarrow X$ satisfying the following properties:

- (a) $F(s, 0) = f(s)$ for all $s \in U$;
- (b) $F(s, t) = f(s)$ for all $s \in \Lambda$ and $t \in V$;
- (c) the partial differential

$$\left. \frac{\partial}{\partial t} \right|_{t=0} F(s, t) : \mathbb{C}^N \longrightarrow T_{f(s)}X$$

is surjective for every $s \in U \setminus \Lambda$.

Under the additional hypotheses that an Oka manifold X satisfies ELS, the proof of the Oka principle for maps $S \rightarrow X$ from 1-convex manifolds requires only minor modifications of the proof in the standard case when S is a Stein manifold; see [14, Chapter 5; 24]. In fact, it suffices to postulate the existence of a holomorphic spray as in the definition of ELS merely in a small open neighborhood of the exceptional variety Λ ; using standard tools (see, e.g., [11]) we can then construct a spray with the stated properties over any relatively compact open subset of S .

Therefore, to complete the proof of Theorem A.1, we need the following lemma.

Lemma A.2. (i) If global holomorphic vector fields on a complex manifold X span the tangent space of X at each point, then X satisfies ELS.

- (ii) Every elliptic manifold satisfies ELS. □

Proof of (i). Fix a 1-convex manifold S , a holomorphic map $f : S \rightarrow X$, and an open relatively compact subset $U \Subset S$ containing the exceptional subvariety Λ of S . Since the set $f(\bar{U}) \subset X$ is compact, the condition on X gives finitely many, holomorphic vector fields V_1, \dots, V_N whose values at any point $x \in f(\bar{U})$ span the tangent space $T_x X$. Let ϕ_t^j denote the flow of V_j . The formula

$$F(s, t_1, \dots, t_N) = \phi_{t_1}^1 \circ \dots \circ \phi_{t_N}^N (f(s)) \in X, \quad s \in S, \tag{A.1}$$

defines a holomorphic map in an open neighborhood of $S \times \{0\}$ in $S \times \mathbb{C}^N$. Clearly, we have $F(s, 0) = f(s)$ for every $s \in S$, and

$$\left. \frac{\partial}{\partial t_j} \right|_{t=0} F(s, t) = V_j(f(s)) \in T_{f(s)}X,$$

for every $s \in S$ and $j = 1, \dots, N$. Our choice of the vector fields V_j implies that F is a dominating holomorphic spray over U .

To get sprays that are independent of the parameter t over the points $s \in \Lambda$ (see property (b) in the definition of ELS), we choose finitely many holomorphic functions g_1, \dots, g_l on U with $\{g_1, \dots, g_l = 0\} = \Lambda$, and replace each term $\phi_{t_j}^j$ in (A.1) by the composition of l terms $\phi_{t_j, k, g_k(s)}^j$, $k = 1, \dots, l$, where $t_j = (t_{j,1}, \dots, t_{j,l}) \in \mathbb{C}^l$ is near the origin. (There is no misprint here: the function $g_k(s)$ appears as a multiplicative factor in the time variable of the flow.) Since $g_k(s) = 0$ for $s \in \Lambda$, each of the maps $\phi_{t_j, k, g_k(s)}^j$ agrees with the identity when $s \in \Lambda$. If, on the other hand, $s \in U \setminus \Lambda$, then $g_k(s) \neq 0$ for some k , and the composition of flows $\phi_{t_j, k, g_k(s)}^j$ for $j = 1, \dots, N$ (and with fixed k) is a spray which is dominating at s . ■

Proof of (ii). Let (E, π, σ) be a dominating spray on X ; that is, $\pi : E \rightarrow X$ is a holomorphic vector bundle and $\sigma : E \rightarrow X$ is a holomorphic map such that $\sigma(0_x) = x$ and the differential $d\sigma_{0_x} : T_{0_x}E \rightarrow T_xX$ maps the subspace E_x of $T_{0_x}E$ surjectively on to T_xX for every $x \in X$. (Here, 0_x is the zero element of the fiber E_x .) We may consider (E, π, σ) as a fiber-dominating spray on the product submersion $S \times X \rightarrow S$ which is independent of the base variable $s \in S$. Let $f : S \rightarrow X$ be a holomorphic map. We associate to f the section $\tilde{f}(s) = (s, f(s))$ of $S \times X \rightarrow S$. The restriction of E to the graph $\tilde{S} = \tilde{f}(S) \subset S \times X$ of f is a holomorphic vector bundle over the 1-convex manifold \tilde{S} . By a standard result (see, e.g., [24, Theorem 2.4]), such a bundle admits finitely many holomorphic sections V_1, \dots, V_N that vanish on the exceptional variety $\tilde{\Lambda} = \tilde{f}(\Lambda)$ and generate the fiber E_z over each point $z = \tilde{f}(s) \in \tilde{S} \setminus \tilde{\Lambda}$. The holomorphic map $F : S \times \mathbb{C}^N \rightarrow X$, defined by

$$F(s, t_1, \dots, t_N) = \sigma(t_1 V_1(\tilde{f}(s)) + \dots + t_N V_N(\tilde{f}(s))),$$

is then a globally defined, dominating holomorphic spray of maps $S \rightarrow X$ with the core map $f = F(\cdot, 0)$. As in the proof of (i) above, we can also construct sprays that are fixed over the exceptional variety. This shows that X satisfies ELS. ■

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