Strong geodetic problem on Cartesian products of graphs

Vesna Iršič ^a Sandi Klavžar ^{a,b,c}

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- ^a Institute of Mathematics, Physics and Mechanics, Ljubljana, Slovenia
- ^b Faculty of Mathematics and Physics, University of Ljubljana, Slovenia
- ^c Faculty of Natural Sciences and Mathematics, University of Maribor, Slovenia

Abstract

The strong geodetic problem is a recent variation of the geodetic problem. For a graph G, its strong geodetic number $\operatorname{sg}(G)$ is the cardinality of a smallest vertex subset S, such that each vertex of G lies on a fixed shortest path between a pair of vertices from S. In this paper, the strong geodetic problem is studied on the Cartesian product of graphs. A general upper bound for $\operatorname{sg}(G \square H)$ is determined, as well as exact values for $K_m \square K_n$, $K_{1,k} \square P_l$, and prisms over $K_n - e$. Connections between the strong geodetic number of a graph and its subgraphs are also discussed.

Keywords: geodetic problem; strong geodetic problem; isometric path problem; Cartesian product; subgraph

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1 Introduction

Covering vertices of a graph with shortest paths is a natural (optimization) problem arising from different applied problems that respectively led to several different graph theory models. The seminal of them, the *geodetic problem* [10], aims to find a smallest subset of vertices of a given graph such that the geodesics between them cover all its vertices, see the review [2]. Recent studies on this problem have focused on characterizations of graphs with large geodetic number [1], on geodesic graphs [19], and connections between the geodetic problem and a block decomposition [5]. Applications

of the geodetic problem can be found in convexity theory [3, 12, 14, 18] and in game theory [8].

Another variation of the problem of covering vertices with shortest paths is the isometric path problem [6] where the aim is to determine the minimum number of shortest paths required to cover all the vertices of a graph. Following [6] this problem has been investigated on Cartesian products of graphs [7], in particular on Hamming graphs as well as on complete r-partite graphs in [17].

Motivated by applications in social networks, the strong geodetic problem was introduced in [15] as follows. Let G = (V, E) be a graph. Given a set $S \subseteq V$, for each pair of vertices $\{x,y\} \subseteq S$, $x \neq y$, let $\widetilde{g}(x,y)$ be a selected fixed shortest path between x and y. We set

$$\widetilde{I}(S) = \{\widetilde{g}(x,y) : x, y \in S\},\$$

and $V(\widetilde{I}(S)) = \bigcup_{\widetilde{P} \in \widetilde{I}(S)} V(\widetilde{P})$. If $V(\widetilde{I}(S)) = V$ for some $\widetilde{I}(S)$, then the set S is called a *strong geodetic set*. For a graph G with just one vertex, we consider the vertex as its unique strong geodetic set. The *strong geodetic problem* is to find a minimum strong geodetic set of G. The cardinality of a minimum strong geodetic set is the *strong geodetic number* of G and is denoted by $\operatorname{sg}(G)$.

In the first paper [15] on the strong geodetic number, this invariant has been determined for complete Apollonian networks and it was proved that the problem is NP-complete. Then, in [13], the problem was studied on grids and cylinders. Among other results it was proved that if r is large enough compared to n, then $\operatorname{sg}(P_r \square P_n) = \lceil 2\sqrt{n} \rceil$. Some general properties of the strong geodesic problem, in particular with respect to the diameter, and a solution for balanced complete bipartite graphs has been very recently reported in [11]. We also refer to [16] for an edge version of the problem.

In this paper, the strong geodesic problem is studied on Cartesian product graphs. In the next section we give several upper bounds on $\operatorname{sg}(G \square H)$ and study their sharpness. In Section 3 we determine the strong geodetic number for several families of Cartesian products, including products of complete graphs. We also discuss a possible lower bound for $\operatorname{sg}(G \square H)$. Motivated by this discussion, in the final section we focus on possible connections between the strong geodetic number of a graph and its subgraphs. But first we list necessary definitions.

All graphs considered in this paper are simple and connected. The distance $d_G(u, v)$ between vertices u and v of a graph G is the number of edges on a shortest u, v-path (u, v-geodesic). The diameter diam(G) of G is the maximum distance between vertices

of G. We denote the order of a graph G by n(G). A vertex v of a graph G is simplicial if its neighborhood induces a clique. We will use the notation $[n] = \{1, \ldots, n\}$ and the convention that $V(P_n) = V(K_n) = V(C_n) = [n]$ for any $n \ge 1$, where the edges of the path P_n , the complete graph K_n , and the cycle C_n are defined in the natural way.

The Cartesian product $G \square H$ of graphs G and H is the graph with vertex set $V(G) \times V(H)$, where the vertices (g,h) and (g',h') are adjacent if either g = g' and $hh' \in E(H)$, or h = h' and $gg' \in E(G)$. If $h \in V(H)$, then a subgraph of $G \square H$ induced by the set of vertices $\{(x,h); x \in V(G)\}$ is isomorphic to G; it is denoted by G^h and called a G-layer, a horizontal layer or a row. Analogously H-layers are defined; if $g \in V(G)$, then the corresponding H-layer, called a vertical layer or a column, is denoted gH . Moreover, if X is a subgraph of G, then its isomorphic copy from the layer G^h will be denoted with X^h . Similarly, if Y is a subgraph of H, then its isomorphic copy in the layer gH will be denoted with gY .

2 Upper bounds on $sg(G \square H)$

The investigations from [13] indicate that it is not easy to determine the strong geodetic number of an arbitrary integer grid, that is, $\operatorname{sg}(P_r \square P_n)$. As these grids are among the simplest Cartesian product graphs, it would be too ambitious to expect a formula for $\operatorname{sg}(G \square H)$. In this section we therefore consider upper bounds for $\operatorname{sg}(G \square H)$ and discuss their sharpness.

Note first that lifting a strong geodetic set of G (resp. H) into each of the G-layers (resp. H-layers) yields $\operatorname{sg}(G \square H) \leq \min\{\operatorname{sg}(G)\operatorname{n}(H),\operatorname{sg}(H)\operatorname{n}(G)\}$. This observation can be improved as follows.

Theorem 2.1 If G and H are graphs, then

$$\operatorname{sg}(G \square H) \le \min \{ \operatorname{sg}(H) \operatorname{n}(G) - \operatorname{sg}(G) + 1, \operatorname{sg}(G) \operatorname{n}(H) - \operatorname{sg}(H) + 1 \}.$$

Proof. Since the Cartesian product operation is commutative, it suffices to prove that $sg(G \square H) \le sg(H) n(G) - sg(G) + 1$.

Let S_G be a strong geodetic set of G, $\widetilde{I}(S_G)$ fixed geodesics in G, S_H a strong geodetic set of H, and $\widetilde{I}(S_H)$ fixed geodesics in H, where $|S_G| = \operatorname{sg}(G) = k$ and $|S_H| = \operatorname{sg}(H) = l$. Set $S_G = \{g_0, g_1, \ldots, g_{k-1}\}$ and $S_H = \{h_0, h_1, \ldots, h_{l-1}\}$. Denote with P_i the g_0, g_i -geodesic from $\widetilde{I}(S_G)$ for all $i \in [k-1]$ and with Q_j the h_0, h_j -geodesic from $\widetilde{I}(S_H)$ for all $j \in [l-1]$.

Define $T = (V(G) \times S_H) - \{(g_i, h_0); i \in [k-1]\}$. Clearly, $|T| = \operatorname{sg}(H) \operatorname{n}(G) - \operatorname{sg}(G) + 1$. We claim that T is a strong geodetic set of $G \square H$. To show it, we first fix geodesics in H-layers between vertices from T in the same way as they are fixed in $\widetilde{I}(S_H)$. The only (possibly) uncovered vertices are the ones lying in H-layers $g_i H$ for $i \in [k-1]$ that lie on paths $g_i Q_j$ for $j \in [l-1]$. To cover them we fix $(g_i, h_j), (g_0, h_0)$ -geodesics as paths $g_i Q_j$ joined with $P_i^{h_0}$ for all $i \in [k-1], j \in [l-1]$. In this way all the vertices of $G \square H$ are covered, hence $\operatorname{sg}(G \square H) \leq |T|$.

If $n \geq 2$, then $\operatorname{sg}(P_n \square K_2) = 3 = \operatorname{sg}(P_n) \operatorname{n}(K_2) - \operatorname{sg}(K_2) + 1$. This example shows that the inequality of Theorem 2.1 is best possible. To construct more sharpness examples we need the following general property.

Lemma 2.2 If G and H are graphs, v is a simplicial vertex of G, and S is a strong geodetic set of $G \square H$, then $S \cap {}^v H \neq \emptyset$.

Proof. Suppose on the contrary that $S \cap {}^v H = \emptyset$. Let $P \in \widetilde{I}(S)$ be an arbitrary geodesic that contains some vertices of ${}^v H$. By the assumption, P starts and ends outside ${}^v H$. Let (g,h) be the first vertex of P with a neighbor in ${}^v H$ and let (g',h') be the first subsequent vertex of P that does not lie in ${}^v H$. Suppose $g \neq g'$. Then a ((g,h),(g,h'))-geodesic together with the edge (g,h')(g',h') (which exists since v is a simplicial vertex of G) yields a shorter ((g,h),(g',h'))-path than the ((g,h),(g',h'))-subpath of P, a contradiction with the fact that P is a geodesic. If g = g' we get the same contradiction, except that there is no need to add the edge (g,h')(g',h').

If $n \geq 3$, then let G_n be the graph obtained from C_{3n} by adding vertices u, v, w and edges $u \sim 1$, $v \sim n + 1$, and $w \sim 2n + 1$; cf. Fig. 1 for G_3 .

Recall from [15] that a simplicial vertex lies in every strong geodetic set. Hence $sg(G_n) \geq 3$. On the other hand, $\{u, v, w\}$ is a strong geodetic set which implies that $sg(G_n) = 3$. (We note that for the geodetic problem the graphs G with the property that the set of simplicial vertices of G is geodetic, were studied under the name extreme geodesic graphs [4].) Consider now the product $G_n \square K_2$. By Lemma 2.2 we have $sg(G_n \square K_2) \geq 3$. Suppose $sg(G_n \square K_2) = 4$ and let S be a strong geodetic set with |S| = 4. Then S must have two vertices in each of the G_n -layers. Thus, applying Lemma 2.2 again, we can assume without loss of generality that $\{(u, 1), (v, 2), (w, 2)\} \subseteq S$. If S is the fourth vertex of S, then S lies in S_n and equals one of S0. Without loss of generality assume that the S1, S2, S3. By Lemma 2.2 again, we can assume without loss of generality assume that the S3 suppose S4 suppose S5. If S6 is the fourth vertex of S6, then S6 lies in S7 and equals one of S8. Without loss of generality assume that the S3 suppose S4 suppose S5. Without loss of generality assume that the S5 suppose S6 suppose S6. Without loss of generality assume that the S6 suppose S

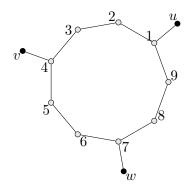


Figure 1: A graph G_3 and its strong geodetic set.

is not possible to cover all vertices $(2n+2,1), (2n+2,2), \ldots, (2n-1,1), (2n-1,2)$, as $n \geq 3$. In conclusion,

$$sg(G_n \square K_2) = 5 = sg(G_n) n(K_2) - sg(K_2) + 1$$

hence we have constructed another infinite family attaining equality in Theorem 2.1.

If G=(V,E) is a graph and $S\subseteq V$, then S is called a 2-packing if $d(x,y)\geq 3$ holds for any $x,y\in S,\ x\neq y$. Equivalently, S is not a 2-packing if and only if S contains vertices $u\neq v$ such that $d(u,v)\leq 2$. Now we can improve Theorem 2.1 in the following case.

Proposition 2.3 If G is a graph with $sg(G) \ge 3$ that admits a strong geodetic set which is not a 2-packing, then

$$\operatorname{sg}(G \square K_n) \le n \operatorname{sg}(G) - n.$$

Proof. Let S be a strong geodetic set of a graph G with the desired properties: $|S| = \operatorname{sg}(G) = k$ and $S = \{u, v, u_1, \dots, u_{k-2}\}$, where $d(u, v) \leq 2$. Let $\widetilde{I}(S)$ be a set of fixed geodesics. Let $P_{uv} \in \widetilde{I}(S)$ be the path between u and v and note that the length of P_{uv} is either 1 or 2. For $i \in [k-2]$ denote by $P_i \in \widetilde{I}(S)$ the u, u_i -geodesic and by $Q_i \in \widetilde{I}(S)$ the v, u_i -geodesic.

Set $T=((S-\{u\})\times\{1\})\cup((S-\{v\})\times\{2,\ldots,n\})$. Clearly, $|T|=n\operatorname{sg}(G)-n$. Fix the same geodesics as in $\widetilde{I}(S)$ between vertices in $(S-\{u\})\times\{1\}$ and between vertices in $(S-\{v\})\times\{j\}$ for all $j\in\{2,\ldots,n\}$. Some possibly uncovered vertices are the ones lying on paths P_i^1 in G^1 and on paths Q_i^j in G^j for $j\in\{2,\ldots,n\}$. Thus we also fix

geodesics P_i^1 joined with the edge $(u,1) \sim (u,2)$ for all $i \in [k-2]$ and geodesics Q_i^j joined with the edge $(v,j) \sim (v,1)$ for all $i \in [k-2]$ and $j \in \{3,\ldots,n\}$.

If d(u,v)=1, all vertices are already covered. If d(u,v)=2 and w is the middle vertex of the path P_{uv} , the only possible uncovered vertices are (w,j) for all $j \in [n]$. These can be covered by fixing geodesics P_{uv}^j in G^j joined with the edge $(v,j) \sim (v,1)$ for all $j \in \{3,\ldots,n\}$ and a geodesic $(v,1) \sim (w,1) \sim (w,2) \sim (u,2)$. Hence, $\operatorname{sg}(G \square K_2) \leq n \operatorname{sg}(G) - n$.

We point out that Proposition 2.3 does not hold in the case when sg(G) = 2, that is, when G is isomorphic to a path [11]. Indeed, if $m \ge 2$, then $sg(P_m \square K_2) = 3$ and $2 sg(P_m) - 2 = 2$.

A special case of this proposition is the following result for prisms.

Corollary 2.4 If G is a graph with $sg(G) \geq 3$ that admits a strong geodetic set S which is not a 2-packing, then

$$\operatorname{sg}(G \square K_2) \le 2\operatorname{sg}(G) - 2.$$

Based on the above ideas, we can state our second main result of this section that generalizes Proposition 2.3 and in a special case decreases by 1 the upper bound of Theorem 2.1.

Theorem 2.5 If G is a graph, and H is a graph with $sg(H) \ge 3$ that admits a strong geodetic set which is not a 2-packing, then

$$\operatorname{sg}(G \square H) \le \operatorname{sg}(H) \operatorname{n}(G) - \operatorname{sg}(G).$$

Proof. Let S_H be a strong geodetic set of a graph H with the desired properties: $|S_H| = \operatorname{sg}(H) = l \geq 3$ and $S_H = \{u, v, h_1, \dots, h_{l-2}\}$, where $d(u, v) \leq 2$. Let $\widetilde{I}(S_H)$ be a set of fixed geodesic that cover V(H). Let $P_{uv} \in \widetilde{I}(S_H)$ be the path between u and v. Denote by $P_i \in \widetilde{I}(S_H)$ a fixed u, h_i -geodesics and by $Q_i \in \widetilde{I}(S_H)$ a fixed v, h_i -geodesics for all $i \in [l-2]$.

Let S_G be a strong geodetic set of G, $\widetilde{I}(S_G)$ fixed geodesics and $|S_G| = \operatorname{sg}(G) = k$. Set $S_G = \{w, g_1, \dots, g_{k-1}\}$. Denote with R_i a fixed w, g_i -geodesic from $\widetilde{I}(S_G)$ for all $i \in [k-1]$.

Set $T = (V(G) \times S_H) - (\{(g_i, u); i \in [k-1]\} \cup \{(w, v)\})$. Clearly, $|T| = \operatorname{sg}(H) \operatorname{n}(G) - \operatorname{sg}(G)$. Geodesics in H-layers between vertices from T are fixed in the same way as in $\widetilde{I}(S_H)$. The only (possibly) uncovered vertices are the ones lying in H-layers g_iH for

 $i \in [k-1]$ that lie on paths ${}^{g_i}P_j$ for $j \in [l-2]$ and those on paths wQ_j in the layer wH for $j \in [l-2]$. Thus we also fix $(g_i, h_j), (w, u)$ -geodesics as paths ${}^{g_i}P_j$ joined with R_i^u for all $i \in [k-1], j \in [l-2]$ and $(w, h_j), (g_i, v)$ -geodesics as paths wQ_j joined with R_i^v for all $i \in [k-1], j \in [l-2]$.

If d(u, v) = 1, all vertices of $G \square H$ are already covered. If d(u, v) = 2 and t is the middle vertex on P_{uv} , then we also fix geodesic $(g_i, v) \sim (g_i, t) \sim (w, t) \sim (w, u)$ for all $i \in [k-1]$. Now all vertices of $G \square H$ are covered, hence $\operatorname{sg}(G \square H) \leq |T|$.

Corollary 2.6 If G and H are graphs with diam(G) = diam(H) = 2 and $sg(G), sg(H) \ge 3$, then

$$sg(G \square H) \le \min\{sg(H) n(G) - sg(G), sg(G) n(H) - sg(H)\}.$$

3 Exact values for some Cartesian products

In this section we determine the strong geodetic number of prisms over $K_n - e$ (Theorem 3.1), of $K_{1,k} \square P_l$ (Proposition 3.2), and of Hamming graphs $K_m \square K_n$ (Theorem 3.3). At the end of the section we pose a conjecture asserting a general lower bound on $\operatorname{sg}(G \square H)$. The conjecture has been verified for small prisms by computer and is, provided it holds true, best possible by the results of this section.

Theorem 3.1 If $n \ge 5$ is an integer, then $\operatorname{sg}(K_n - e) = \operatorname{sg}((K_n - e) \square K_2) = n - 1$.

Proof. Let $G = K_n - e$ and $e = \{u, v\}$, $u \nsim v$. Denote $V(G) = \{u, v, x_1, \dots, x_{n-2}\}$. As G is not a complete graph, it follows from [11] that $\operatorname{sg}(G) \leq n-1$. Let S be a minimum strong geodetic set of G. As vertices u and v are simplicial, $u, v \in S$. Any u, v-geodesic covers exactly one other vertex, say x_{n-2} . Thus $S - \{u, v\}$ is a strong geodetic set of $G - \{u, v, x_{n-2}\}$, a complete graph on n-3 vertices. Hence, $\operatorname{sg}(G) \geq 2 + \operatorname{sg}(K_{n-3}) = n-1$.

We now prove that $\operatorname{sg}(G \square K_2) \leq n-1$. Consider $S = \{(u,1), (u,2), (v,1), (v,2)\}$ and $T = \{(x_i,1); i \in \{4,\ldots,n-2\}\}$. Geodesics between vertices from S can be fixed in such a way that $\{(x_i,j); i \in [3], j \in [2]\}$ are all covered. The remaining uncovered vertices can be covered with geodesics $(x_i,1) \sim (x_i,2) \sim (u,2)$. Hence, $S \cup T$ is a strong geodetic set of the graph $G \square K_2$ and $\operatorname{sg}(G \square K_2) \leq |S \cup T| = 4 + (n-5) = n-1$.

It remains to prove that $\operatorname{sg}(G \square K_2) \ge n-1$. Notice that the longest geodesics and the only ones of length 3 in graph $G \square K_2$ are (u,1),(v,2)- and (u,2),(v,1)-geodesics. All other geodesics are of length 1 or 2 and can therefore cover at most one K_2 -layer.

Furthermore, any K_2 -layer that is not covered with one of the longest geodesics must contain at least one vertex from the strong geodetic set. Let S be the minimum strong geodetic set of $G \square K_2$ and $\widetilde{I}(S)$ the fixed geodesics. Consider the following cases.

- (a) If $\widetilde{I}(S)$ contains two longest geodesics, then geodesics between vertices $\{(u,1), (u,2), (v,1), (v,2)\}$ can cover five different K_2 -layers. To cover the remaining n-5 K_2 -layers, S must contain at least n-5 more vertices. Hence, $|S| \geq n-1$.
- (b) If $\widetilde{I}(S)$ contains only one of the longest geodesics, this geodesic lies in three K_2 -layers. To cover the remaining n-3 K_2 -layers, we need at least n-3 more vertices. Hence, $|S| \geq 2 + (n-3) = n-1$.
- (c) If $\widetilde{I}(S)$ contains none of the longest geodesics, then at most one vertex among $\{(u,1),(u,2),(v,1),(v,2)\}$ lies in S. Thus at least n-1 K_2 -layers are still completely uncovered, hence $|S| \geq n-1$.

It follows from the above, that $sg(G \square K_2) \ge n - 1$.

Notice that Theorem 3.1 does not hold for $n \leq 4$, as $sg(K_4 - e) = 3 < 4 = sg((K_4 - e) \square K_2)$.

We now derive two exact results for Cartesian products which are not prisms.

Proposition 3.2 If k, l are integers, $k \ge 5$ and $l \ge 1$, then $\operatorname{sg}(K_{1,k} \square P_l) = \operatorname{sg}(K_{1,k})$.

Proof. The graph $K_{1,k}$ is a tree with k leaves, hence $\operatorname{sg}(K_{1,k}) = k$ and $\operatorname{sg}(K_{1,k} \square P_l) \ge k$.

Let $V(K_{1,k}) = \{v, l_1, \dots, l_{k-2}, r_1, r_2\}$ where v is the vertex of degree k. Define $S = \{(l_1, l), \dots, (l_{k-2}, l), (r_1, 1), (r_2, 1)\}$. As shortest paths in $K_{1,k}$ and P_l are unique, x, y-geodesic can be denoted by $x \rightsquigarrow y$. Fix geodesics between vertices from S in the following way:

$$(l_i, l) \sim (v, l) \sim (r_i, l) \rightsquigarrow (r_i, 1)$$

for $i \in [2]$,

$$(l_i, l) \sim (v, l) \leadsto (v, 1) \sim (r_2, 1)$$

for $i \in \{3, ..., k-2\}$, and

$$(l_i, l) \leadsto (l_i, 1) \sim (v, 1) \sim (r_{f(i)}, 1),$$

where

$$f(i) = \begin{cases} 2; & i = 1, \\ 1; & i \neq 1. \end{cases}$$

Clearly, these geodesics cover all vertices of the graph (as $k-2 \geq 3$), hence $sg(K_{1,k} \square P_l) = k$.

Proposition 3.2 does not hold for $k \leq 4$ if $l \geq 3$ (the cases $l \in \{1,2\}$ are simple). Consider the following example. Let $V(K_{1,4}) = \{v, l_1, l_2, r_1, r_2\}$ as above. Suppose $\operatorname{sg}(K_{1,4} \square P_l) = 4$. If $K_{1,4}^l$ (or equivalently $K_{1,4}^1$) contains only one vertex from a minimum strong geodetic set, say l_1 , then geodesics from (l_1, l) to the other three vertices must contain vertices $(l_2, l), (r_1, l), (r_2, l), (l_1, l-1)$ which is not possible. Hence, any strong geodetic set of size 4 contains two vertices in the layer $K_{1,4}^1$ and two vertices in $K_{1,4}^l$. Without loss of generality let $S = \{(l_1, l), (l_2, l), (r_1, 1), (r_2, 1)\}$ be a minimum strong geodetic set. Geodesics $(l_1, l) \sim (v, l) \sim (l_2, l)$ and $(r_1, 1) \sim (v, 1) \sim (r_2, 1)$ are clearly fixed. Each of the remaining four geodesics can cover at most l-1 uncovered vertices. But the graph has 4(l-1) + (l-2) vertices to cover, hence $\operatorname{sg}(K_{1,4} \square P_l) \geq 5$. Since the set $S \cup \{(v, 1)\}$ is a strong geodetic set, we have $\operatorname{sg}(K_{1,4} \square P_l) = 5$.

Our last exact result is the following.

Theorem 3.3 If m, n are positive integers and $m \geq n$, then

$$sg(K_m \square K_n) = \begin{cases} 2n - 1; & m = n, \\ 2n; & n < m < 2n, \\ m; & m \ge 2n. \end{cases}$$

Proof. Since every vertex of a complete graph is simplicial, Lemma 2.2 implies that any strong geodetic set of $K_m \square K_n$ contains at least one vertex from each row and at least one vertex from each column, hence $\operatorname{sg}(K_m \square K_n) \ge \max\{m,n\} = m$. We now distinguish three cases.

1. Suppose first m=n. By the above, $\operatorname{sg}(K_n \square K_n) \geq n$. Take n vertices, one in each row and one in each column. Since $\operatorname{diam}(K_n \square K_n) = 2$, these n vertices can cover at most $\binom{n}{2}$ other vertices of $K_n \square K_n$. Moreover, at most one row and at most one column can be covered completely with geodesics between them. Hence, at least $\binom{n}{2}$ vertices of $K_n \square K_n$ remain uncovered. As at least n-1 rows and columns are still uncovered, it follows that at least n-1 more vertices are needed to cover them. Therefore, $\operatorname{sg}(K_n \square K_n) \geq n + (n-1) = 2n-1$.

Consider the set $S = S_1 \cup S_2$ where $S_1 = \{(i, i); i \in [n]\}$ and $S_2 = \{(i, i + 1); i \in [n - 1]\}$ (cf. Fig. 2).

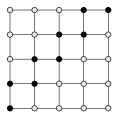


Figure 2: A strong geodetic set of $K_5 \square K_5$.

Fix geodesics for $\widetilde{I}(S)$ in such a way that geodesics between vertices from S_1 cover all the vertices $\{(i,j);\ i\geq j\}$ and geodesics between vertices from S_2 cover the vertices $\{(i,j);\ i< j\}$. Thus S is a strong geodetic set of size 2n-1. Hence, $\operatorname{sg}(K_n \square K_n) = 2n-1$.

2. Suppose next n < m < 2n. Consider an arbitrary strong geodetic set S' of $K_m \square K_n$. Since S' contains at least one vertex from each row and at least one vertex from each column, we may without loss of generality assume that $S_1 \cup S_2 \subseteq S'$, where $S_1 = \{(i,i); i \in [n]\}$ and $S_2 = \{(n+i,i); i \in [m-n]\}$. Consider the disjoint sets

$$A = [m-n] \times \{m-n+1, \dots, n\},$$

$$B = \{n+1, \dots, m\} \times \{m-n+1, \dots, n\},$$

$$C = \{m-n+1, \dots, n\} \times [m-n],$$

$$D = \{(i,j); i < j, i, j \in \{m-n+1, \dots, n\}\}, \text{ and }$$

$$E = \{(i,j); i > j, i, j \in \{m-n+1, \dots, n\}\},$$

which are shown in Fig. 3 for the case $K_{10} \square K_7$.

Vertices in A can only be covered with geodesics between vertices from S_1 , thus these geodesics cannot cover C. The set B can only be covered with geodesics between vertices from S_1 and S_2 and thus these geodesics cannot cover C. Hence, C is left uncovered. Similarly we observe that either D or E is left uncovered. It follows that vertices lying in 2n - m different columns and vertices from n - 1 different rows are left uncovered. To cover them, at least min $\{2n - m, n - 1\}$

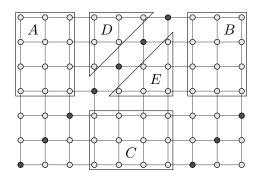


Figure 3: Sets A, B, C, D and E of $K_{10} \square K_7$.

additional vertices must be added to $S_1 \cup S_2$. As m > n, we have $\min\{2n - m, n - 1\} = 2n - m$. Hence, $\operatorname{sg}(K_m \square K_n) \ge m + (2n - m) = 2n$.

Consider the set $S = S_1 \cup S_2 \cup S_3$, where S_1 and S_2 are as above and $S_3 = \{(i,1); i \in \{m-n+1,\ldots,n\}\}$ (cf. Fig. 4). Denote $S_1 = S_1^d \cup S_1^u$, where $S_1^d = \{(i,i); i \in [m-n]\}$ and $S_1^u = \{(i,i); i \in \{m-n+1,\ldots,n\}\}$.

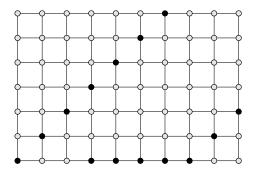


Figure 4: A strong geodetic set of $K_{10} \square K_7$.

Fix geodesics between vertices in S_1 to cover $\{(i,j);\ i < j, i, j \in [n]\}$, geodesics between vertices in S_2 to cover $\{(i,j);\ i < j, i \in \{n+1,\ldots,m\}, j \in [m-n]\}$, geodesics between S_1^d and S_2 to cover $\{(i,j);\ i > j, i \in [m-n] \cup \{n+1,\ldots,m\}, j \in [m-n]\}$ and geodesics between S_1^u and S_2 to cover $\{n+1,\ldots,m\} \times \{m-n+1,\ldots,n\}$. Additionally, fix geodesics $(v,1) \sim (v,i) \sim (i,i)$ for each $v \in S_3$ and $i \in [n]$. Now it is clear that S is a strong geodetic set of size 2n. Hence, $\operatorname{sg}(K_m \square K_n) = 2n$.

3. Suppose finally $m \geq 2n$. We already know that $\operatorname{sg}(K_m \square K_n) \geq m$. Define $S = S_l \cup S_m \cup S_r$, where

$$S_l = \{(i,i); i \in [n]\},$$

 $S_m = \{(i,1); i \in \{n+1,\ldots,m-n\}\}, \text{ and }$
 $S_r = \{(m-n+i,i); i \in [n]\},$

cf. Fig. 5, where S is shown for the case $K_{12} \square K_4$.

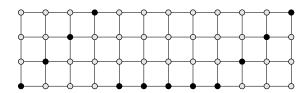


Figure 5: A strong geodetic set of $K_{12} \square K_4$.

Fix geodesics between vertices from S_l to cover vertices $\{(i,j); i \geq j, i, j \in [n]\}$, geodesics between vertices from S_r to cover $\{(m-n+i,j); i \geq j, i, j \in [n]\}$, geodesics between sets S_l and S_r to cover $\{(i,j); i \leq j, i, j \in [n]\} \cup \{(m-n+i,j); i \leq j, i, j \in [n]\}$ and geodesics between a vertex $v \in S_m$ and vertices from S_l to cover $\{(v,i); i \in [n]\}$. Hence S is a strong geodetic set of $K_m \square K_n$ and |S| = m. We conclude that $\operatorname{sg}(K_m \square K_n) = m$.

From Theorem 3.3 we infer that among Cartesian products of complete graphs the upper bound of Theorem 2.1 is sharp only for $K_1 \square K_1$, $K_2 \square K_2$, and $K_3 \square K_2$.

Until now we have considered general upper bounds on $sg(G \square H)$ and obtained several exact values. Hence it would also be of interest to have some general lower bound(s). For this sake we pose:

Conjecture 3.4 If G is a graph with $n(G) \ge 2$, then $sg(G \square K_2) \ge sg(G)$.

If Conjecture 3.4 is true, then it is best possible as demonstrated by Theorem 3.1. We have also verified the conjecture by computer for all graphs G with $n(G) \leq 7$. The equality is never attained for $n(G) \leq 3$. For n(G) = 4 the only equality case is $G = K_4$, while for n(G) = 5 and 6 there are more equality cases. For n(G) = 5 all of them are shown in Fig. 6.

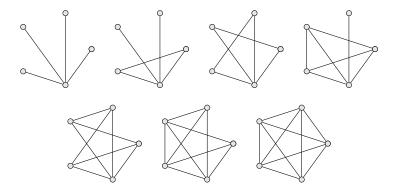


Figure 6: Graphs G on five vertices with $sg(G) = sg(G \square K_2)$.

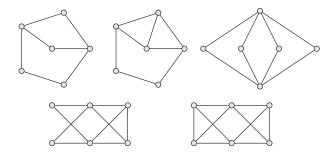


Figure 7: Graphs G on six vertices with $sg(G) = sg(G \square K_2)$ and no simplicial vertex.

For n(G) = 6 the variety of equality graphs is too large to be drawn here. Instead we present in Fig. 7 those of them that do not contain simplicial vertices.

More generally as Conjecture 3.4, we pose the following

Problem 3.5 Is it true that if G and H are graphs, then $sg(G \square H) \ge max\{sg(G), sg(H)\}$?

Again, if the answer to Problem 3.5 is positive, then the result is best possible as demonstrated by Proposition 3.2 and by Theorem 3.3 for $m \ge 2n$.

4 The strong geodetic number of subgraphs

Since layers of Cartesian products are subgraphs that possess several distinguishing properties, a way to attack Conjecture 3.4 would be to understand the relation between the strong geodetic number of a graph and its subgraphs. This is a fundamental

question for any graph invariant and has not yet been studied for the strong geodetic number. The main message of this section is that in general there is no such relation, even for subgraphs with a very special structure such as layers in products.

Induced subgraphs

First we observe that there is no connection between a strong geodetic number of the graph and a strong geodetic number of its (induced) subgraph.

Let $G_n = P_{2n} \square K_2$ and H_n its subgraph induced on vertices $V(G_n) - \{(2i, 1); i \in [n]\}$ (cf. Fig. 8). Clearly, $\operatorname{sg}(G_n) = 3$, as $\{(1, 1), (2n, 1), (2n, 2)\}$ is a strong geodetic set. The subgraph H_n is a tree with n + 1 leaves, thus $\operatorname{sg}(H_n) = n + 1$. Hence, the strong geodetic number of an induced subgraph can be arbitrarily larger than the strong geodetic number of a graph. The converse is also true. Consider $H = P_n$ as $\operatorname{a}(n)$ (induced) subgraph of some tree T. It holds $\operatorname{sg}(H) = 2$, but the strong geodetic number of T can be arbitrarily large (and equals the number of its leaves).

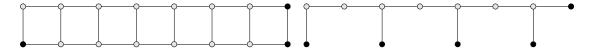


Figure 8: The strong geodetic sets of graphs G_4 and its subgraph H_4 .

Convex subgraphs

A subgraph H of graph G is *convex* if every shortest path in G between vertices from H lies entirely in H. This is a stronger concept than induced subgraphs. Layers of Cartesian products are convex.

As paths are convex subgraphs of trees, it is clear that the strong geodetic number of a graph can be arbitrarily larger than the strong geodetic number of its convex subgraphs. The following example shows that the converse also holds.

Let $k, l \in \mathbb{N}$. Define $G_{k,l}^c$ to be the graph with $V(G_{k,l}^c) = \{u_1, \ldots, u_k\} \cup \{w\} \cup \{x_1, y_1, \ldots, x_{kl}, y_{kl}\} \cup \{v_1, \ldots, v_l\}$ and edges $w \sim u_i$ for $i \in [k]$, $w \sim x_i$ for $i \in [kl]$, $x_i \sim y_i$ for $i \in [kl]$ and $y_i \sim v_j$ for all $i \in [kl]$ and $j \in [l]$ (cf. Fig. 9). Let H be its subgraph induced by $\{w\} \cup \{x_1, \ldots, x_{kl}\}$. Note that H is a convex subgraph with $\mathrm{sg}(H) = kl$ (as it is a tree).

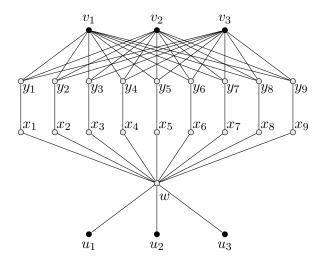


Figure 9: The graph $G_{3,3}^c$.

As vertices $\{u_1, \ldots, u_k\}$ are simplicial, they lie in any strong geodetic set of $G_{k,l}^c$. But due to the structure of the graph, each vertex v_i must also lie in any strong geodetic set. Hence, $\operatorname{sg}(G_{k,l}^c) \geq k+l$. Consider the set $S = \{u_1, \ldots, u_k\} \cup \{v_1, \ldots, v_l\}$ and fix the geodesics $u_i \sim w \sim x_{(i-1)l+j} \sim y_{(i-1)l+j} \sim v_j$ for all $i \in [k]$ and $j \in [l]$. These geodesics cover all vertices of the graph, hence $\operatorname{sg}(G_{k,l}^c) = k+l$, which is arbitrarily smaller than kl, the strong geodetic number of the convex subgraph H.

Gated subgraphs

A subgraph H of graph G is gated if for every $v \in V(G)$ there exists an $x \in V(H)$ that lies on a shortest u, v-path for every $u \in V(H)$. Every gated subgraph is convex [9]. Layers of Cartesian product are not only convex but also gated.

Unfortunately, there is also no connection between the strong geodetic number of a graph and its gated subgraphs. Again, as paths are gated subgraphs of trees, the strong geodetic number of a graph can be arbitrarily larger than the strong geodetic number of its gated subgraphs. The following example shows that the converse is also true

Let $k, l \in \mathbb{N}$ such that $kl \geq 5$. Define the graph $G_{k,l}^g$ with vertices $\{x, y\} \cup \{v_{i,j}; i \in [k], j \in [l]\} \cup \{x_1, \dots, x_k\} \cup \{y_1, \dots, y_l\}$ and edges $x \sim x_i$ for $i \in [k], y \sim y_j$ for $j \in [l], x \sim v_{i,j} \sim y$ for $i \in [k], j \in [l]$ (cf. Fig. 10).

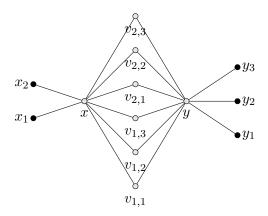


Figure 10: The graph $G_{2,3}^g$.

Let $S = \{x_1, \ldots, x_k, y_1, \ldots, y_l\}$. Vertices in S are all simplicial, thus $\operatorname{sg}(G_{k,l}^g) \ge |S| = k + l$. If we fix geodesics $x_i \sim x \sim v_{i,j} \sim y \sim y_j$ for all $i \in [k], j \in [l]$, then it is clear that S is a strong geodetic set. Hence, $\operatorname{sg}(G_{k,l}^g) = k + l$.

Let H be a subgraph of G induced on the vertex set $\{x,y\} \cup \{v_{i,j}; i \in [k], j \in [l]\}$. Clearly, $H \cong K_{2,kl}$. The subgraph H is gated in G. It follows from $kl \geq 5$, that $\binom{kl-1}{2} \geq kl$ and thus by [11] it holds that $\operatorname{sg}(H) = kl$. Hence, the strong geodetic number of a gated subgraph can be arbitrarily larger than the strong geodetic number of a graph.

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