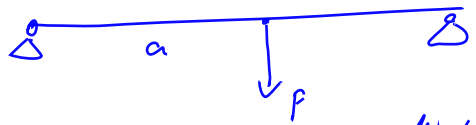


$$M = \frac{EI}{R} ; R = -\frac{d^2w}{dx^2} ; \frac{d^2M}{dx^2} = -q(x) \Rightarrow \frac{d^2}{dx^2} (EI \frac{d^2w}{dx^2}) - q = 0$$

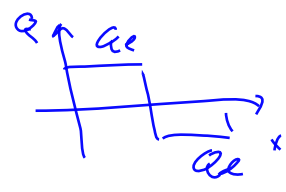
$$\frac{dQ}{dx} = -q$$



Vaje 20. maj 2021

1. Za konzolno vpeti nosilec z enakomerno obremenitvijo  $q_0$ :

- določi upogib nosilca;
- določi maksimalen upogib.

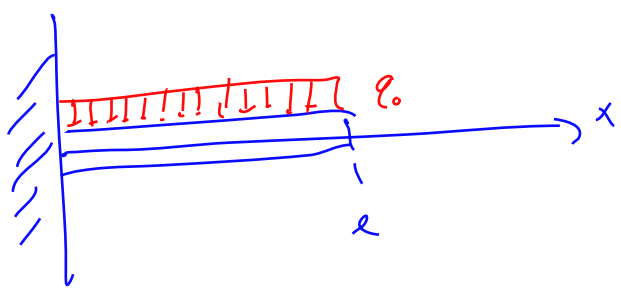


$$w_l(a) = w_d(a)$$

$$w'_l(a) = w'_d(a)$$

$$w''_l(a) = w''_d(a) \leftarrow$$
~~$$w'''_l(a) = w'''_d(a) \leftarrow$$~~

$$\frac{dM}{dx} = Q \Rightarrow Q = -EI \frac{d^3w}{dx^3}$$



$$Q_l(a) - F = Q_d(a)$$

$$(-EI w''_l(a) - F) = -EI w''_d(a)$$

$$w'''' = \frac{q_0}{EI}$$

$$w''' = \frac{q_0}{EI} x + C_1$$

$$w'' = \frac{1}{2} \frac{q_0}{EI} x^2 + C_1 x + C_2$$

$$w' = \frac{1}{6} \frac{q_0}{EI} x^3 + \frac{1}{2} C_1 x^2 + C_2 x + C_3 \leftarrow$$

$$w = \frac{1}{24} \frac{q_0}{EI} x^4 + \frac{1}{6} C_1 x^3 + \frac{1}{2} C_2 x^2 + C_3 x + C_4 \leftarrow$$

$$w(0) = 0$$

$$w'(0) = 0$$

$$M(l) = 0, Q(l) = 0$$

$$w'''(l) = 0$$

$$w(0) = 0 \Rightarrow C_4 = 0$$

$$w'(0) = 0 \Rightarrow C_3 = 0$$

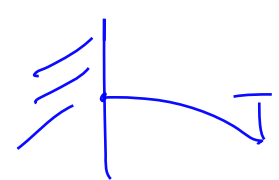
$$\frac{q_0 l}{EI} + C_1 = 0 \Rightarrow C_1 = -\frac{q_0 l}{EI}$$

$$\frac{1}{2} \frac{q_0 l^2}{EI} + C_1 l + C_2 = 0$$

$$C_2 = -\frac{1}{2} \frac{q_0 l^2}{EI} - C_1 l = \frac{q_0 l^2}{EI} \left(-\frac{1}{2} + 1\right) = \frac{q_0 l^2}{2EI}$$

$$w = \frac{q_0}{24EI} x^4 - \frac{1}{6} \frac{q_0 l}{EI} x^3 + \frac{1}{2} \frac{q_0 l^2}{2EI} x^2 = \frac{q_0}{2EI} x^2 \left( \frac{1}{12} x^2 - \frac{1}{3} lx + \frac{1}{2} l^2 \right)$$

$$w = \frac{q_0 l^2}{2EI} x^2 \left( \frac{1}{12} \left(\frac{x}{l}\right)^2 - \frac{1}{3} \frac{x}{l} + \frac{1}{2} \right)$$



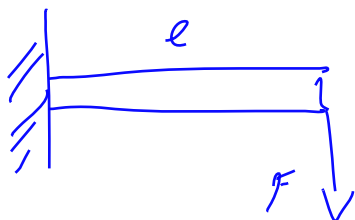
$f(x)$  na  $[a, b]$ ; Kje  $f(x)$  doseže maksimum?

V točki, kjer je  $f'(x)=0$  ali na krajščih.

$$w_{\max} = w(x=l) = \frac{q_0 l^2}{2EI} l^2 \left( \frac{1}{12} - \frac{1}{3} + \frac{1}{2} \right) = \frac{q_0 l^4}{8EI}$$
$$\frac{1-2+6}{12} = \frac{1}{2}$$

2. Za konzolno vpeti nosilec s točkovno obremenitvijo na koncu:

- določi upogib nosilca;
- določi maksimalen upogib in ga primerjaj z maksimalnim upogibom enakomerno obremenjenega nosilca.



$$EI w'''' = 0$$

$$w'''' = 0$$

$$w = C_1 x^3 + C_2 x^2 + C_3 x + C_4$$

$$w(0) = 0, w'(0) = 0$$

$$w''(l) = 0 \quad Q = -EI w'''' ; \quad w''''(l) = -\frac{F}{EI}$$

$$w(0) = 0 \Rightarrow C_4 = 0 ; \quad w'(0) = 0 \Rightarrow C_3 = 0$$

$$w' = 3C_1 x^2 + 2C_2 x + C_3$$

$$w'' = 6C_1 x + 2C_2$$

$$w''' = 6C_1$$

$$w''''(l) = -\frac{F}{EI} = 6C_1 \Rightarrow C_1 = -\frac{F}{6EI} \checkmark$$

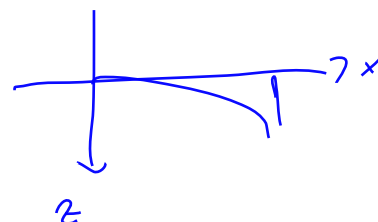
$$0 = w''(l) = 6C_1 l + 2C_2 \Rightarrow C_2 = -\frac{3}{2} C_1 l = \frac{Fl}{2EI}$$

$$w = -\frac{F}{6EI} x^3 + \frac{Fl}{2EI} x^2 = \frac{Fl}{2 \cdot 6EI} \left( -\frac{x^3}{3} + \frac{1}{l} l x^2 \right) =$$

$$= \frac{Fl^2}{2 \cdot 6EI} x^2 \left( -\frac{x}{3l} + \frac{1}{l} \right)$$

$$w_{\max} = w(x=l) = \frac{Fl^3}{2 \cdot 6EI} \left( -\frac{1}{3} + \frac{1}{1} \right)$$

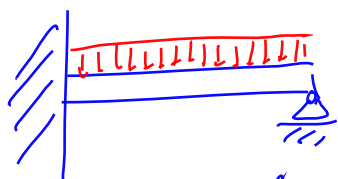
$$= \frac{Fl^3}{2 \cdot 6EI} \cdot \frac{2}{3} = \frac{Fl^3}{9EI}$$



$$w_{\max} = \frac{Fl^3}{3EI}$$



3. Konzolno vpeti nosilec z enakomerno obremenitvijo z gosoto  $q_0$  je na koncu členkasto podprt. Določi upogib nosilca in silo podpore na koncu.



$$EI w'''' = q_0$$

$$w = \frac{q_0}{24EI} x^4 + C_1 x^3 + C_2 x^2 + C_3 x + C_4$$

$$w(0) = 0, w'(0) = 0; \quad w(l) = 0; \quad w''(l) = 0$$

$$C_3 = C_4 = 0$$

$$w' = \frac{q_0}{6EI} x^3 + 3C_1 x^2 + 2C_2 x$$

$$w'' = \frac{q_0}{2EI} x^2 + 6C_1 x + 2C_2$$

$$6C_1 l + 2C_2 = -\frac{q_0 l^2}{2EI}$$

$$C_1 l^3 + C_2 l^2 = -\frac{q_0 l^4}{24EI}$$

$$C_1 l + C_2 = -\frac{q_0 l^2}{24EI} \quad | \cdot (-2) |$$

$$4C_1 l = -\frac{q_0 l^2}{EI} \left( \frac{1}{2} - \frac{1}{12} \right) = -\frac{5q_0 l^2}{12EI} \Rightarrow C_1 = -\frac{5q_0 l}{48EI}$$

$$C_2 = -C_1 l - \frac{q_0 l^2}{24EI} = \frac{q_0 l^2}{EI} \left( +\frac{5}{48} - \frac{1}{24} \right) = \frac{q_0 l^2}{48EI} (5-2)$$

$$C_2 = \frac{3q_0 l^2}{48EI} = \frac{q_0 l^2}{16EI}$$

$$w = \frac{q_0}{24EI} x^4 - \frac{5q_0 l}{48EI} x^3 + \frac{q_0 l^2}{16EI} x^2 =$$

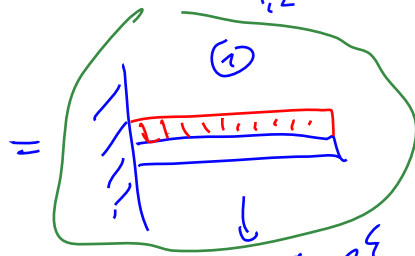
$$= \frac{q_0}{48EI} x^2 \left( 2x^2 - 5lx + 3l^2 \right) = \frac{q_0 l^2}{48EI} x^2 \left( 2\left(\frac{x}{l}\right)^2 - 5\frac{x}{l} + 3 \right)$$

5

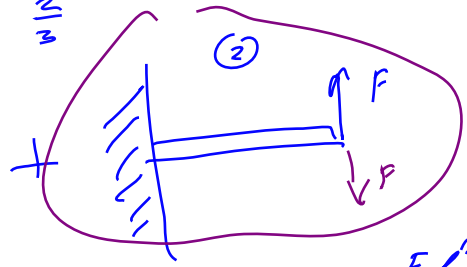
$$w' = \frac{q_0}{6EI} x^3 - \frac{5q_0 l}{16EI} x^2 + \frac{q_0 l^2}{8EI} x = \frac{q_0}{2EI} x \left( \frac{1}{3} x^2 - \frac{5}{8} lx + \frac{1}{4} l^2 \right)$$

$$\frac{1}{3}x^2 - \frac{5}{8}lx + \frac{1}{4}l^2 = 0$$

$$x_{1,2} = \frac{\frac{5}{8}l \pm \sqrt{\frac{25}{64}l^2 - \frac{1}{3}l^2}}{\frac{2}{3}}$$



$$W_1(l) = \frac{q_0 l^4}{8EI}$$



$$W_2(l) = \frac{Fl^3}{3EI}$$

$$W = W_1 + W_2 ; 0 = W(l) = \frac{q_0 l^4}{8EI} + \frac{Fl^3}{3EI} = 1 \quad F = -\frac{3q_0 l}{8}$$

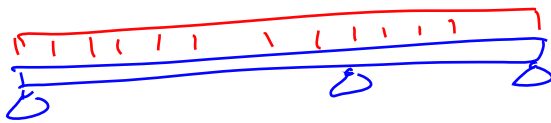
$$W_1 = \frac{q_0 x^2}{24EI} (x^2 - 4lx + 6l^2)$$

$$W_2 = \frac{F}{6EI} x^2 (-x + 3l) = -\frac{q_0 l}{6EI} x^2 (-x + 3l)$$

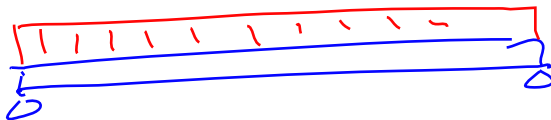
$$W_1 + W_2 = \frac{q_0 x^2}{8EI} \left( \frac{1}{3}x^2 - \frac{4}{3}lx + 2l^2 + \frac{1}{2}x - \frac{3}{2}l^2 \right) =$$

$$= \frac{q_0 x^2}{8EI} \left( \frac{1}{3}x^2 - \frac{5}{6}lx + \frac{1}{2}l^2 \right)$$

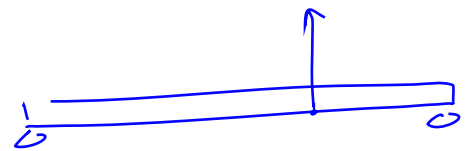
$$\frac{1}{2} - \frac{4}{3} = \frac{3-8}{6}$$



=



+



4. Enostavno podprti nosilec je na sredini obremenjen s točkovnim upogibnim momentom  $M_0$ .

(a) Določi upogib nosilca.

(b) Skiciraj upogib in določi maksimalni upogib.

