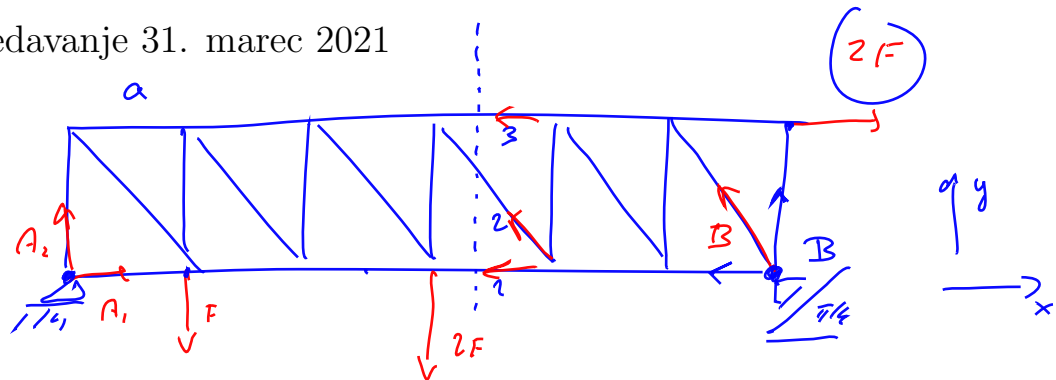


Predavanje 31. marec 2021



$$\vec{A} = A_1 \vec{i} + A_2 \vec{j} \quad ; \quad \vec{B} = B \left( -\frac{1}{\sqrt{2}} \vec{i} + \frac{1}{\sqrt{2}} \vec{j} \right)$$

Metoda prereza

Primer: določitev sil v izbranih palicah.

$$-6a A_2 + 5a F + 3a \cdot 2F - a 2F = 0$$

$$A_2 = \frac{1}{6} (5 + 6 - 2) F = \frac{3}{2} F$$

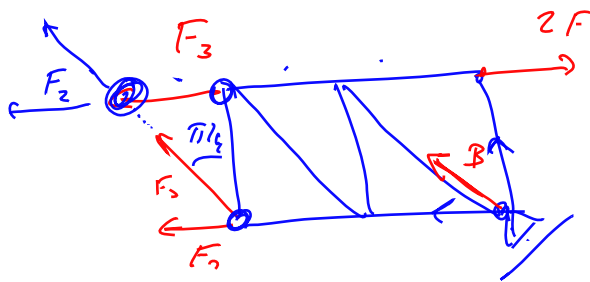
$$6a \frac{1}{\sqrt{2}} B - a F - 3a \cdot 2F - a 2F = 0$$

$$B = \frac{\sqrt{2}}{6} (1 + 6 + 2) F = \frac{3}{2} \sqrt{2} F = \frac{3}{\sqrt{2}} F$$

$$A_1 - B \frac{1}{\sqrt{2}} + 2F = 0 \Rightarrow A_1 = B \frac{1}{\sqrt{2}} - 2F = \frac{3}{2} F - 2F = -\frac{1}{2} F$$

$$A_2 - F - 2F + \frac{1}{\sqrt{2}} B = \frac{3}{2} F - 3F + \frac{3}{2} F = 0 \checkmark$$

② Navidezen preiz:



$$a F_3 - a 2F + 2a \frac{1}{\sqrt{2}} B = 0 \Rightarrow F_3 = 2F - 2 \frac{3}{2} F = -F \checkmark$$

$$-a F_1 - a \frac{1}{\sqrt{2}} B + 3a \frac{1}{\sqrt{2}} B = 0 \Rightarrow F_1 = -\frac{1}{\sqrt{2}} B + 3 \frac{1}{\sqrt{2}} B = 2 \frac{3}{2} \frac{1}{\sqrt{2}} B = \frac{3}{\sqrt{2}} F$$

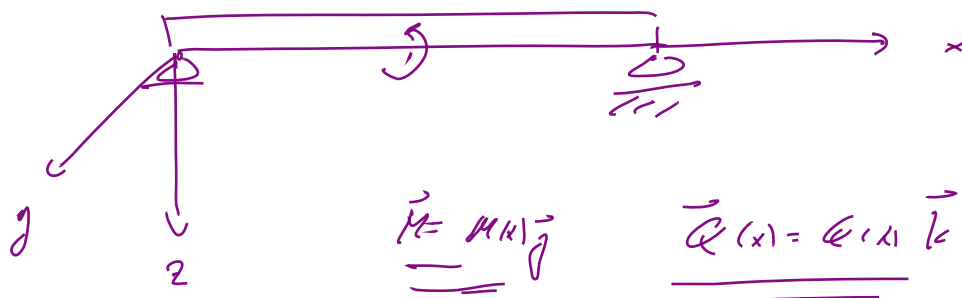
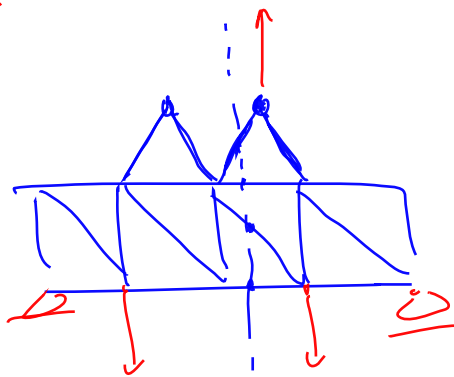
$$\frac{1}{\sqrt{2}} F_2 + \frac{1}{\sqrt{2}} B = 0 \Rightarrow F_2 = -B = -\frac{3}{\sqrt{2}} F \checkmark$$

$$-F_1 - \frac{1}{\sqrt{2}} F_2 - F_3 - \frac{1}{\sqrt{2}} B + 2F = 0$$

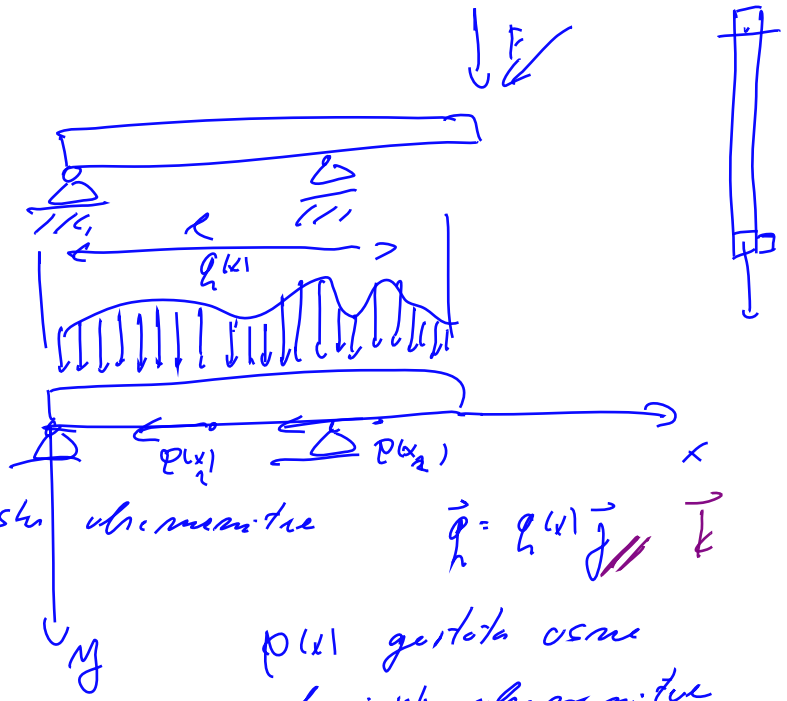
$$-3F - \frac{3}{2}F + \frac{3}{2}F + F - \frac{3}{2}F + 2F = 0 \checkmark$$

Primerjava vozliščne metode in metode prereza.

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# Ravninski nosilci



primere  
 $q(x)$  gostota linijske obremenitve  $\vec{q} = q(x) \vec{j}$   
 $p(x)$  gostota osne linijske obremenitve

## Linijska obremenitev nosilca

Rezultanta linijske obremenitve je integral gostote linijske obremenitve

$$\vec{F} = \int_0^l (q(x) \vec{j} + p(x) \vec{i}) dx = \int_0^l p(x) dx \vec{i} + \int_0^l q(x) dx \vec{j}$$

Konstantna linijska obremenitev  
 ||  
 gostota je konstantna

Ekvipolentna točkovna obremenitev.

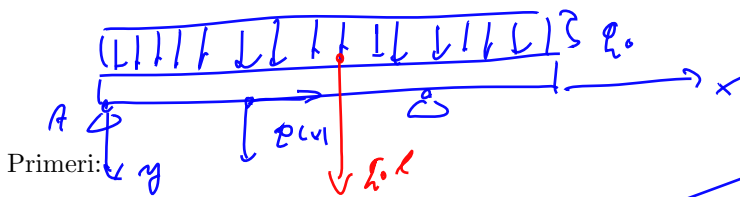
$$q(x) = q_0$$

$$\int_0^l q_0 dx = \int_0^l q_0 dx = q_0 l$$

$$[q_0] = \frac{N}{m}$$

$$q(x) = q_0 x$$

linearna obremenitev



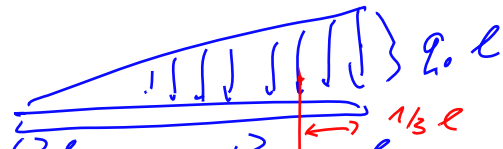
Primeri:

- enakomerna (konstantna) porazdelitev;

$$\vec{N} = \vec{N}(A) = \int_0^l x q(x) dx \vec{i}$$

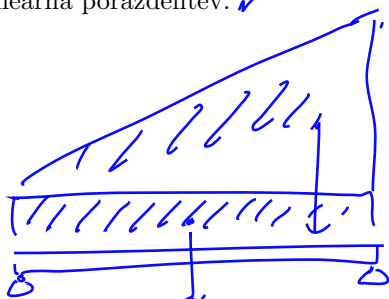
$$r = \frac{\int_0^l x q(x) dx}{\int_0^l q(x) dx}$$

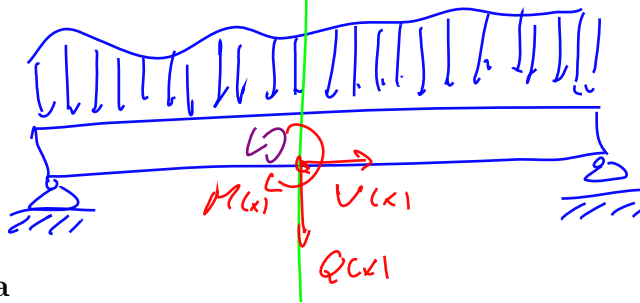
$$r = \frac{\int_0^l x q(x) dx}{\int_0^l q(x) dx} = \frac{N}{F}$$



$$\int_0^l q(x) dx = \frac{1}{2} l \cdot q_0$$

- linearna porazdelitev.





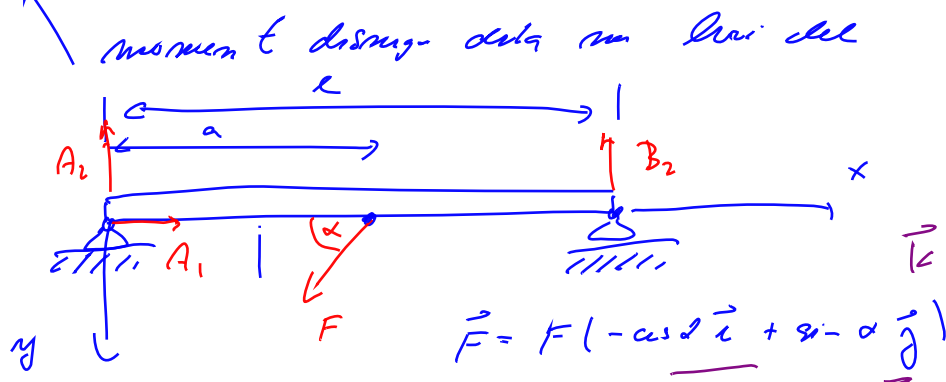
## Notranje količine nosilca

Navidezni prerez nosilca.

- osna sila  $V(x)$ ;
- prečna sila  $Q(x)$ ;
- upogibni moment  $M(x)$ .

sila desno delo nosilca na levi del nosilca  
 v osni smeri pri navideznem prerez  
 prerez  $x$

upogibni smeri  
 pozitivna v  
 obratni smeri  
 usmerna lažalca



## Določitev notranjih količin z metodo prereza

Primer: točkovno obremenjen enostavno podprt nosilec:

- potek osne sile;
- potek prečne sile;
- potek upogibnega momenta.

$$-lB_2 + aF\sin\alpha = 0$$

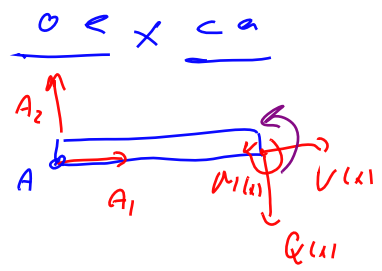
$$B_2 = \frac{a}{l} F\sin\alpha$$

$$lA_2 - (l-a)F\sin\alpha = 0$$

$$A_2 = \frac{l-a}{l} F\sin\alpha$$

$$A_1 - F\cos\alpha = 0 \quad A_1 = F\cos\alpha$$

$$A_2 + B_2 - F\sin\alpha = F\sin\alpha - F\sin\alpha = 0$$



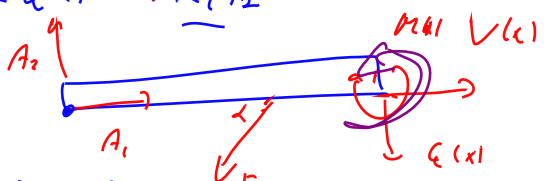
u skrajnih

$$A_1 + V(x) = 0 \Rightarrow V(x) = -A_1$$

$$-A_2 + Q(x) = 0 \Rightarrow Q(x) = A_2$$

$$xQ(x) + (-M(x)) = 0 \Rightarrow -M(x) = +xQ(x) = +xA_2$$

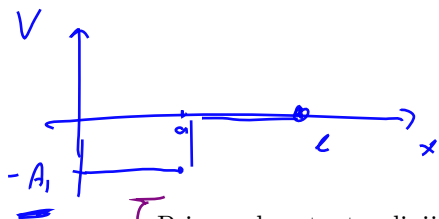
$a < x < l$



$$A_1 - F\cos\alpha + V(x) = 0 \Rightarrow V(x) = -A_1 + F\cos\alpha$$

$$-A_2 + F\sin\alpha + Q(x) = 0 \Rightarrow Q(x) = A_2 - F\sin\alpha = \left(\frac{l-a}{l} - 1\right)F\sin\alpha = -\frac{a}{l}F\sin\alpha$$

$$aF\sin\alpha + xQ(x) + (-M(x)) = 0 \Rightarrow -M(x) = -xQ(x) - aF\sin\alpha = -x\left(-\frac{a}{l}F\sin\alpha\right) - aF\sin\alpha = \frac{ax}{l}F\sin\alpha - aF\sin\alpha$$



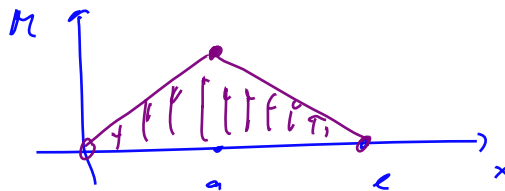
Primer: konstantna linijska obremenitev enostavno podprtega nosilca:

- potek osne sile;
- potek prečne sile;
- potek upogibnega momenta.

$$M(x) = -x A_2 + F_{s1-x} (x-a) \quad M(x) = x A_2 - F_{s1-x} (x-a)$$

$$Q(x=0) = A_2$$

$$Q(x=l) = -B_2$$



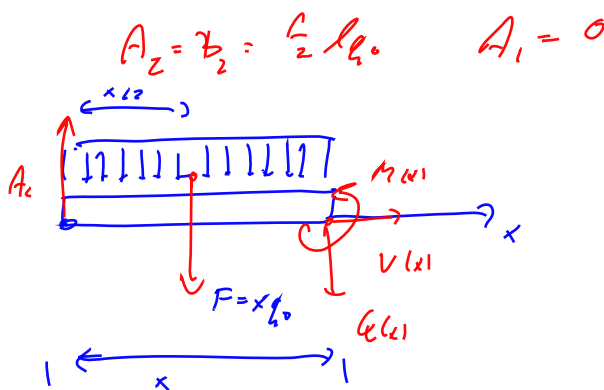
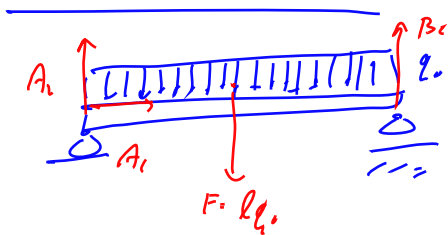
$$a < x < l \Rightarrow M(x) = x A_2 - (x-a) F_{s1-x} =$$

$$= x \frac{l-a}{l} F_{s1-x} - (x-a) F_{s1-x} =$$

$$= F_{s1-x} \left( x \left(1 - \frac{a}{l}\right) - (x-a) \right) =$$

$$= F_{s1-x} \left( a - \frac{a}{l} x \right)$$

$$M(x=l) = F_{s1-x} \left( a - \frac{a}{l} \cdot l \right) = 0$$



$$0 + V(x) = 0$$

$$- A_2 + x q_0 + Q(x) = 0$$

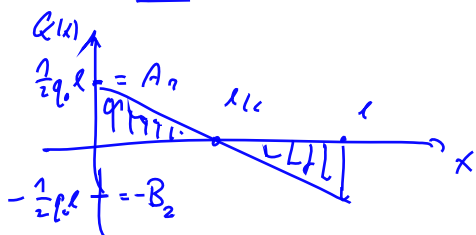
$$Q(x) = A_2 - x q_0 = \frac{l}{2} q_0 - x q_0$$

$$Q(x) = \underline{q_0 \left( \frac{l}{2} - x \right)}$$

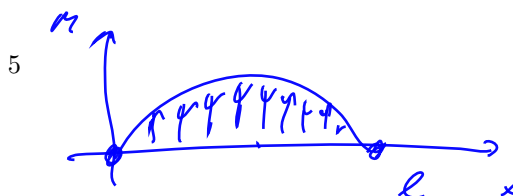
$$-\frac{x}{2} \cdot x q_0 - x Q(x) + M(x) = 0 \Rightarrow M(x) = \frac{q_0}{2} x^2 + x Q(x) =$$

$$= \frac{q_0}{2} x^2 + x q_0 \left( \frac{l}{2} - x \right) =$$

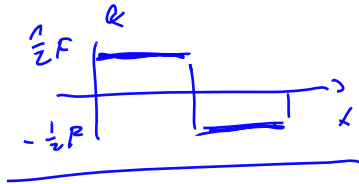
$$= q_0 \left( \frac{1}{2} x l - \frac{1}{2} x^2 \right) = \underline{\underline{\frac{q_0}{2} x (l-x)}}$$



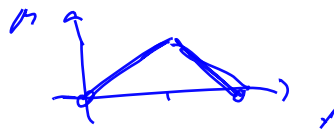
$$Q(x=l) = -B_2; \quad Q(x=0) = A_2$$



Točkovna obremenitev



$a = l/2, \quad d = \pi/2; \quad F = q_0 \cdot l$



$\lim_{x \rightarrow 0} M - A_2 + Q(x) = 0$

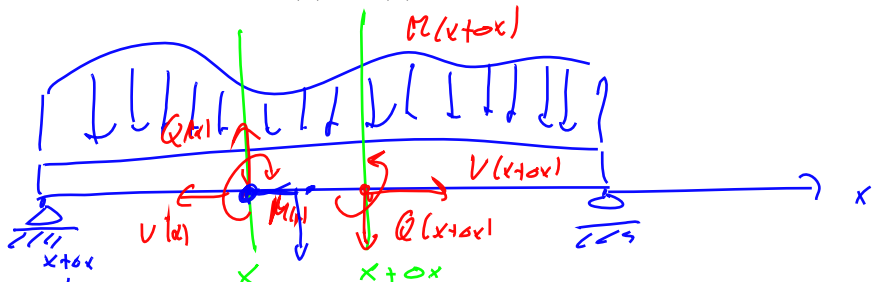
$Q(x=l) = A_2$

Ugotovitve: pri enostavno podprtem nosilcu velja:

1. prečna sila je na levem krajišču enaka sili leve podpore;
2. prečna sila je na desnem krajišču enaka negativni vrednosti sili desne podpore;
3. prečna sila ima pri točkovni obremenitvi v točkah obremenitve nezveznosti s skokom, ki je enak sili obremenitve v tej točki;
4. upogibni moment je enak nič v krajiščih;
5. upogibni moment je pri točkovno obremenjenem nosilcu odsekoma linearen.

**Določitev notranjih količin z diferencialno metodo**

Izpeljava formul za zvezno linijsko obremenitev  $p(x)\vec{i} + q(x)\vec{k}$ .



$x: \quad \underline{V(x+dx) - V(x)} + \int_x^{x+dx} p(s) ds = 0 \quad \text{za vsak } dx$

1.  $\lim_{dx \rightarrow 0} \left( \frac{V(x+dx) - V(x)}{dx} + \frac{1}{dx} \int_x^{x+dx} p(s) ds = 0 \right) \Rightarrow \frac{dV}{dx} + p(x) = 0 \Rightarrow \underline{\frac{dV}{dx} = -p(x)}$   
 p razreda k laci

2:  $Q(x+dx) - Q(x) + \int_x^{x+dx} q(s) ds = 0 \Rightarrow \underline{\frac{dQ}{dx} = -q(x)}$

Če je linijska obremenitev zvezna v okolici  $x_0$ , potem pri  $x = x_0$  veljajo ravnovesne enačbe

$\underline{\underline{\frac{dV}{dx} = -p(x), \quad \frac{dQ}{dx} = -q(x), \quad \frac{dM}{dx} = Q(x)}}$

$M(x+dx) - M(x) - dx \cdot Q(x+dx) - \int_x^{x+dx} (s-x) q(s) ds = 0 \quad \frac{1}{dx}; \quad \lim_{dx \rightarrow 0}$   
 $\left( \frac{dM}{dx} - Q(x) \right) - \lim_{s \rightarrow x} (s-x) q(s) = 0$

$$A: Q(x+dx) = Q(x)$$

$dx \rightarrow 0$

konstanta

$$\frac{dM}{dx} = Q(x)$$

Primer: linearna linijska obremenitev enostavno podprtega nosilca.

$$\frac{dV}{dx} = -p(x); \quad \frac{dQ}{dx} = -q(x); \quad \int \frac{dM}{dx} = Q(x) \quad \begin{array}{l} p(x) = 0 \\ q(x) = +q_0 \end{array}$$

$$\frac{dV}{dx} = 0 \Rightarrow V = \text{konst.} = 0$$

$$\frac{dQ}{dx} = -q_0 \Rightarrow Q(x) = -q_0 x + C_1 \quad Q(x=0) = A_2 = C_1$$

$$\frac{dM}{dx} = Q(x) = -q_0 x + C_1 \Rightarrow M = -\frac{1}{2} q_0 x^2 + C_1 x + C_2$$

$$M(x=0) = 0 \quad \text{in} \quad M(x=l) = 0$$

$\Downarrow$

$$C_2 = 0$$

$$-\frac{1}{2} q_0 l^2 + C_1 l = 0 \Rightarrow C_1 = \frac{1}{2} q_0 l$$

$$M(x) = -\frac{1}{2} q_0 x^2 + \frac{1}{2} q_0 l x = \underline{\underline{\frac{1}{2} q_0 x (l-x)}}$$

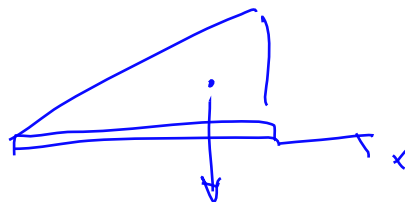
linearna linijska  $q(x) = x q_0$

$$\frac{dQ}{dx} = -q(x) = -x q_0 \Rightarrow Q = -\frac{1}{2} q_0 x^2 + C_1$$

$$\frac{dM}{dx} = Q(x) = -\frac{1}{2} q_0 x^2 + C_1 \Rightarrow M = -\frac{1}{6} q_0 x^3 + C_1 x + C_2$$

$$M(x=0) = M(x=l) = 0$$

7



Primer: konstantna linijska obremenitev konzolnega nosilca.